

# Challenges for Next-Generation 3D Displays

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Tokyo University of Agriculture and Technology*

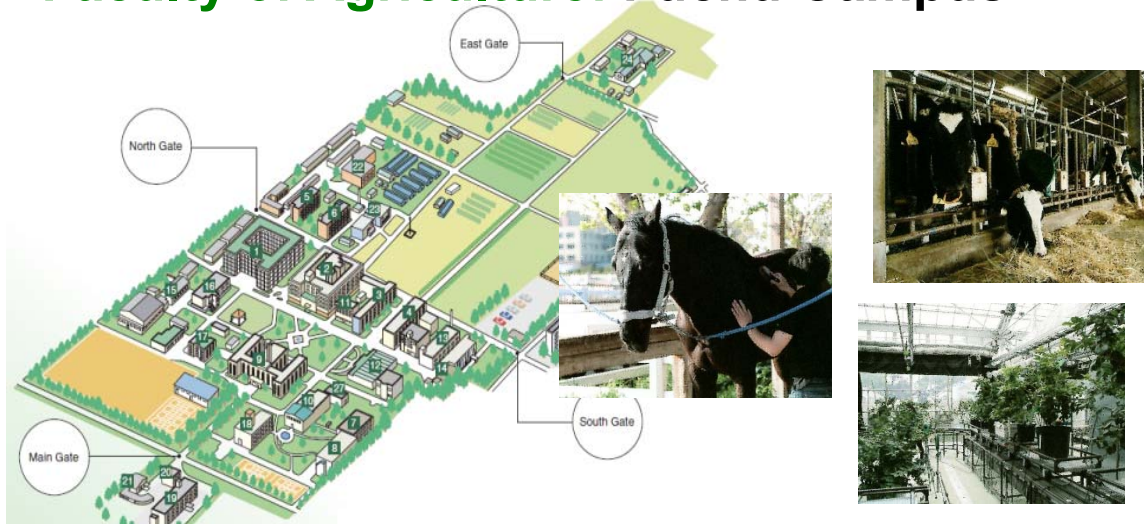
# TUAT

## Tokyo University of Agriculture and Technology

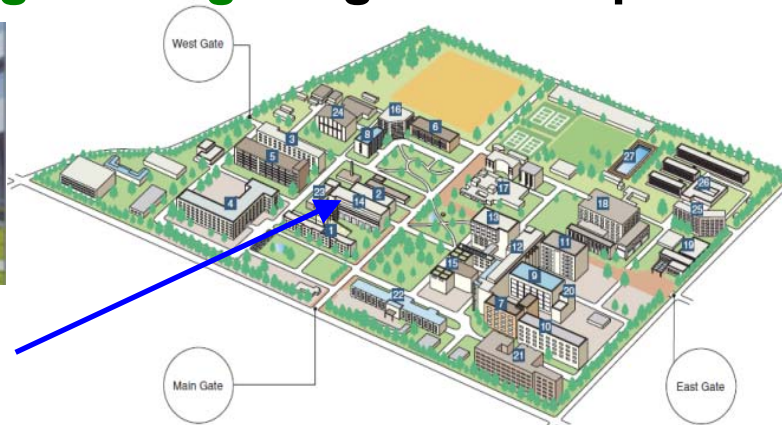
<http://www.tuat.ac.jp>

Established in 1877, National University in Japan

### Faculty of Agriculture: Fuchu Campus



### Faculty of Engineering: Koganei Campus



**We are here !**

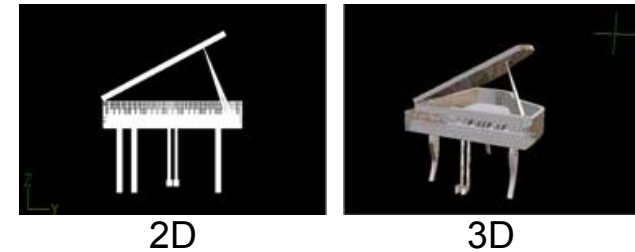
**40 min. from Tokyo Station**  
**2 hours from Narita**  
**1.5 hours from Haneda**

Undergraduates: 3,849  
 Postgraduates: 1,893  
 Faculty & Staff: 650  
 (2015)

# Why Do We Need 3D Displays ?

## 1. Depth information

Structures of objects and scenes can be understood easily and precisely.



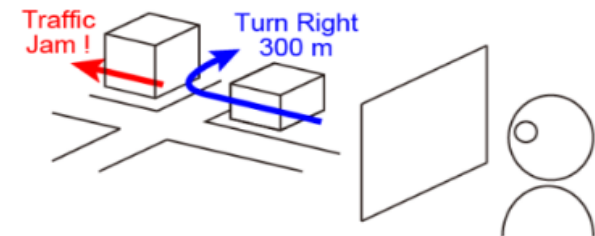
## 2. High reality & presence

We feel as if real objects existed or we were in real world.



## 3. Advanced man-machine interface

Digital information is provided at the same depth of real objects.



## 4. Object appearance reproduction

Directional light reflection on object surfaces causes gloss, transparency, softness, etc.



# Effective Applications of 3D Displays

## Endoscopic & robotic surgery



da Vinci



## Robot manipulation



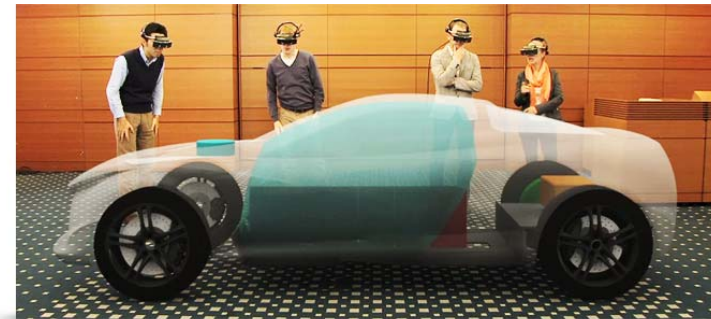
YANMAR



## Virtual experiences



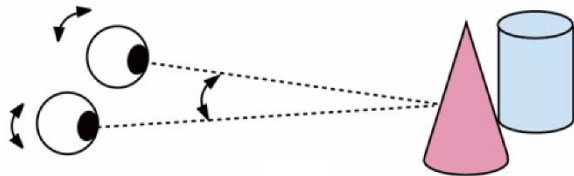
## Design



CANON, MR System

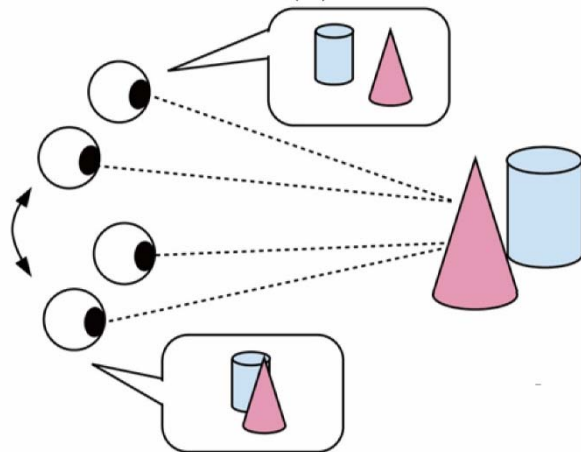
## and Future TV...

# 3D Perception: Physiological Factors



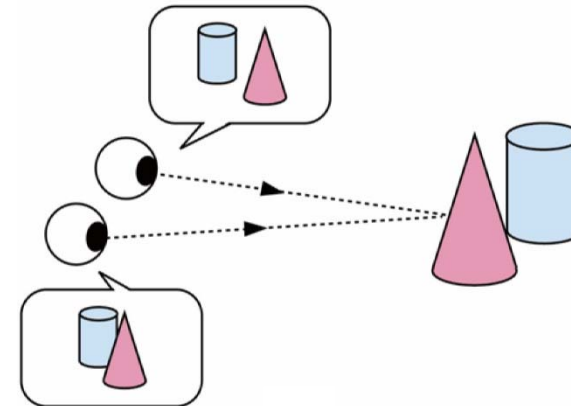
## Vergence

the angle between the lines of sight when the left and the right eyes see the same point



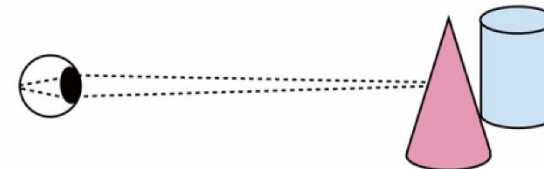
## Motion parallax

the change in a retinal image due to the movement of eyes



## Binocular disparity

the horizontal displacement in retinal images between the left and right eyes

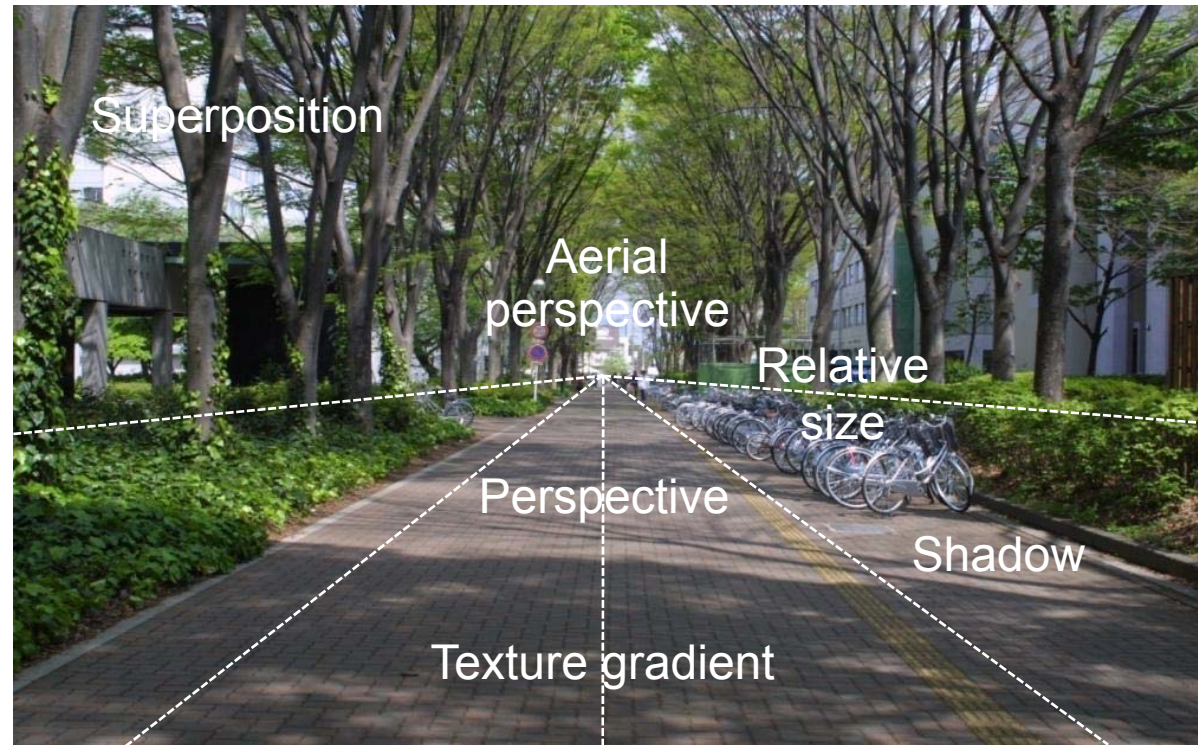


## Accommodation

the change of the focal length of the lenses in the eyes when focusing on an object

*Harmony among these four factors is the key to developing comfortable 3D displays.*

# 3D Perception: Psychological Factors



*Psychological factors are important in the creation of effective 3D content.*

# Present 3D Displays

## Eye-glasses based

- TV
- LC shutter glasses, polarizing glasses
- Vergence, binocular parallax



## Glasses-free: two-view

- Mobile, game
- Single viewer
- Vergence, binocular parallax



## Glasses-free: multi-view

- PC monitor, advertisement
- ~ 9 views, multiple viewers
- Vergence, binocular parallax, motion parallax

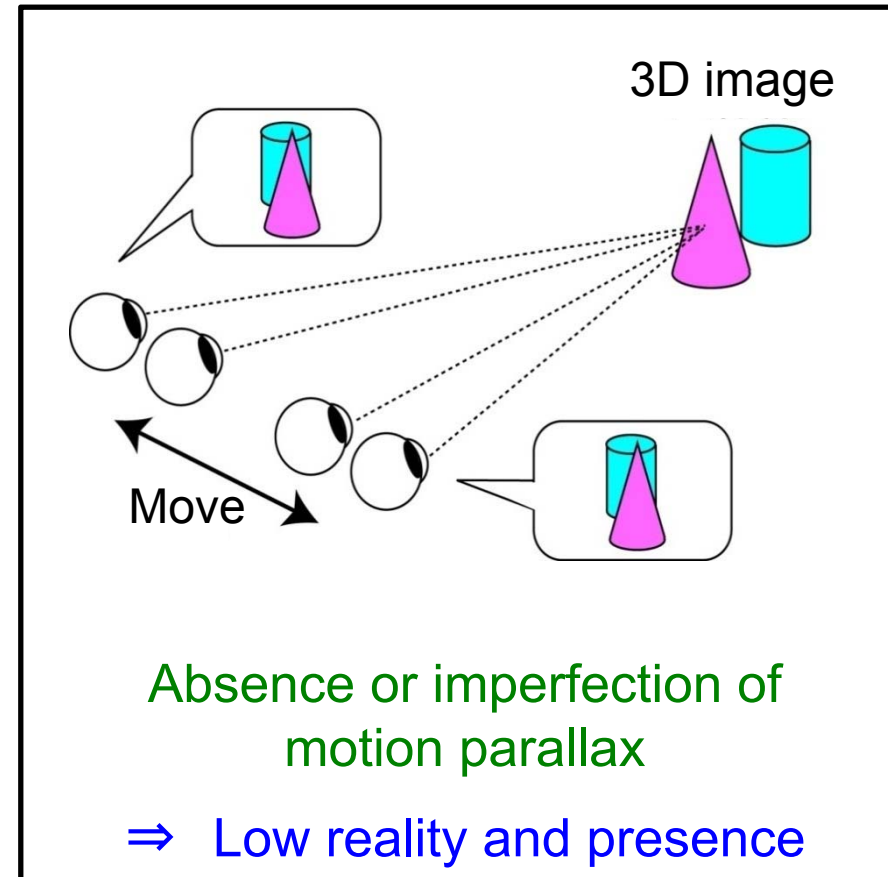
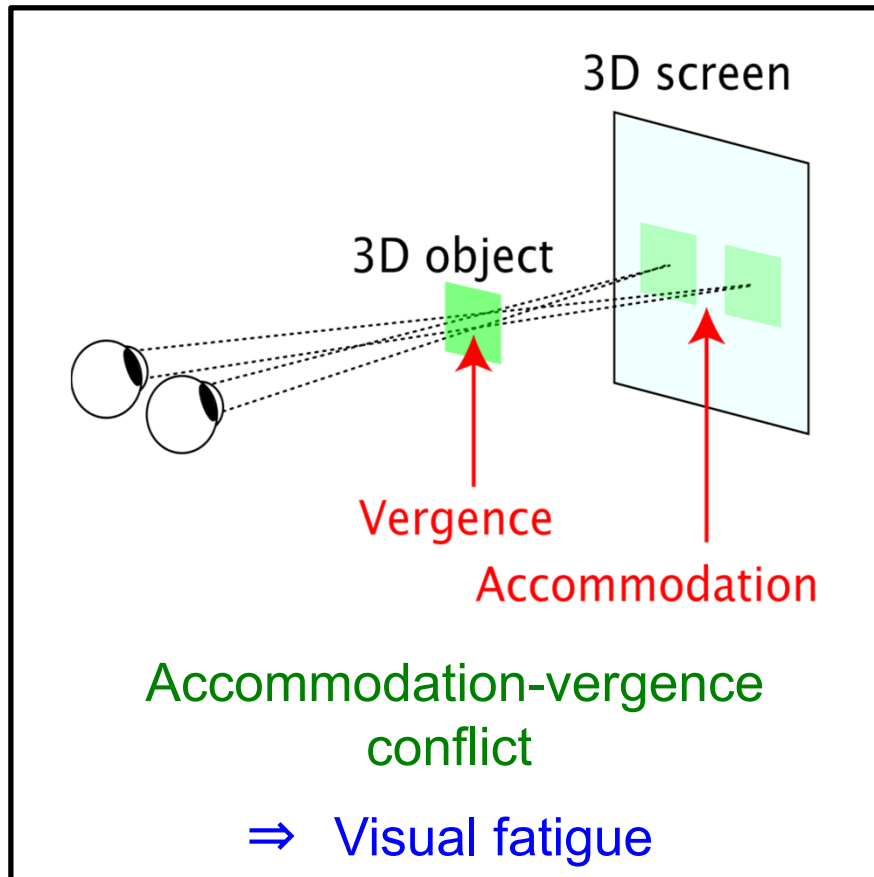


## Head-mount display

- Game, VR
- Head tracking
- Vergence, binocular parallax



# Problems of Present 3D Displays



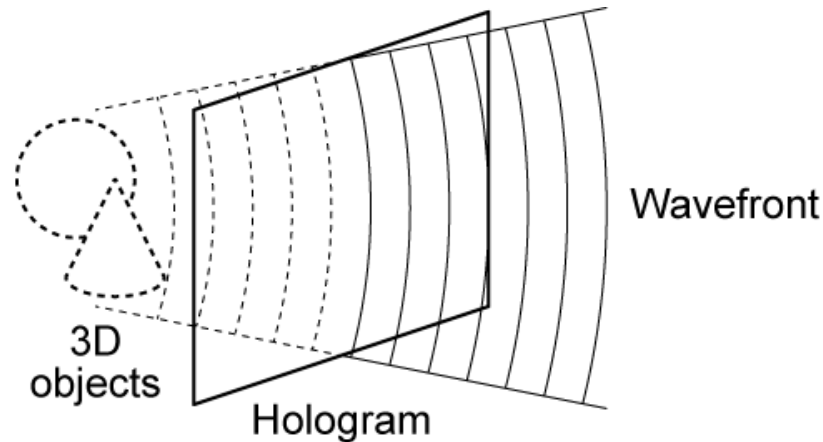
*A natural 3D display, which is free from these two problems, needs to be developed as a next-generation 3D display.*



# Classification of 3D Display Techniques

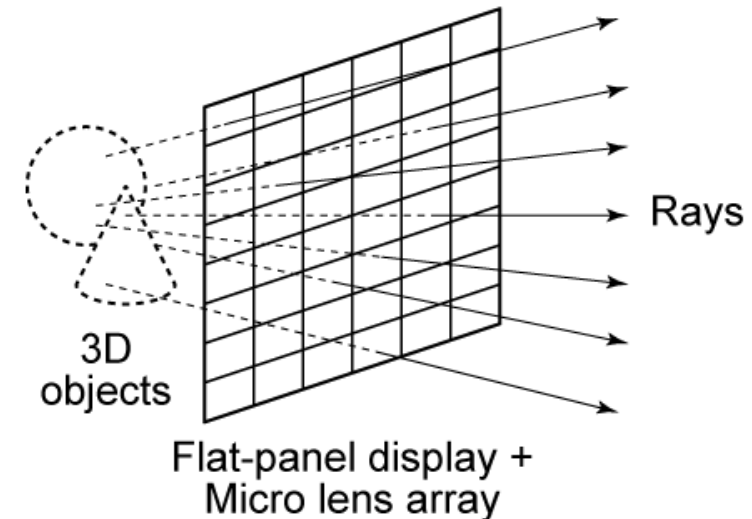
## Wavefront reconstruction

Holography



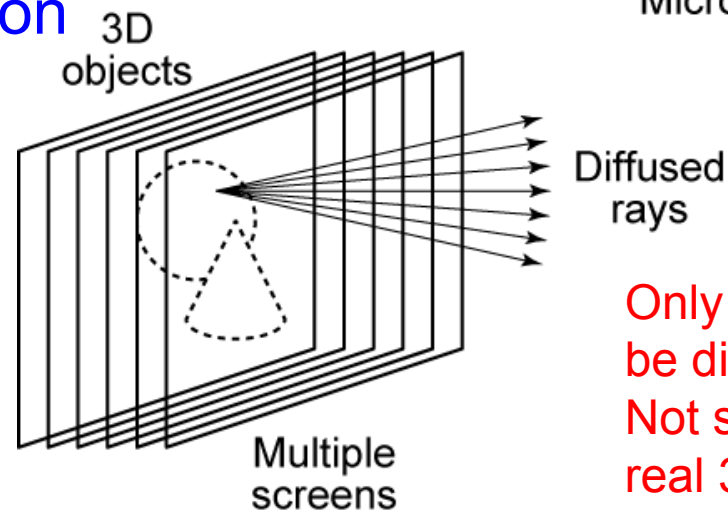
## Ray reconstruction

Multi-view, integral imaging



## Volume reconstruction

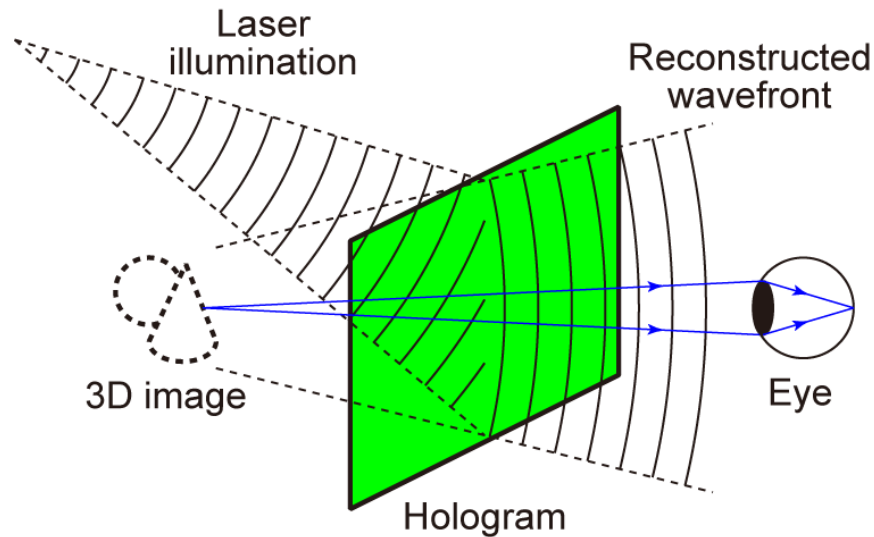
Stack of 2D images



Only diffusive objects can be displayed.  
Not suitable for displaying real 3D images.

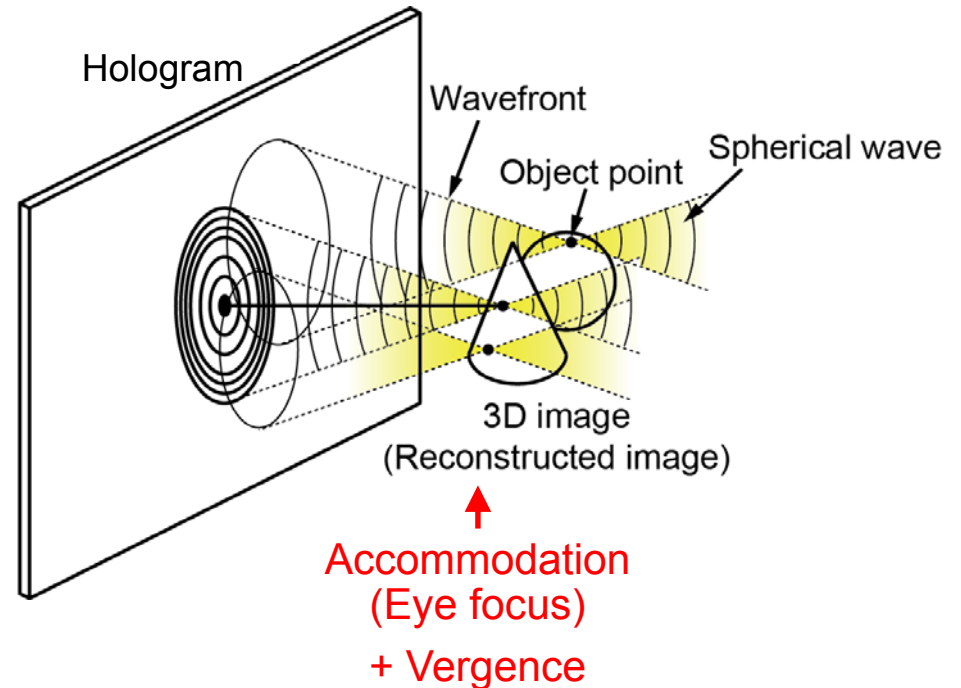
# Holography

Holography was invented by D. Gabor, who was awarded the Nobel Prize in 1971.



Wavefront emitted from 3D objects are reconstructed.

Vergence	○
Binocular disparity	○
Accommodation	○
Motion parallax	○



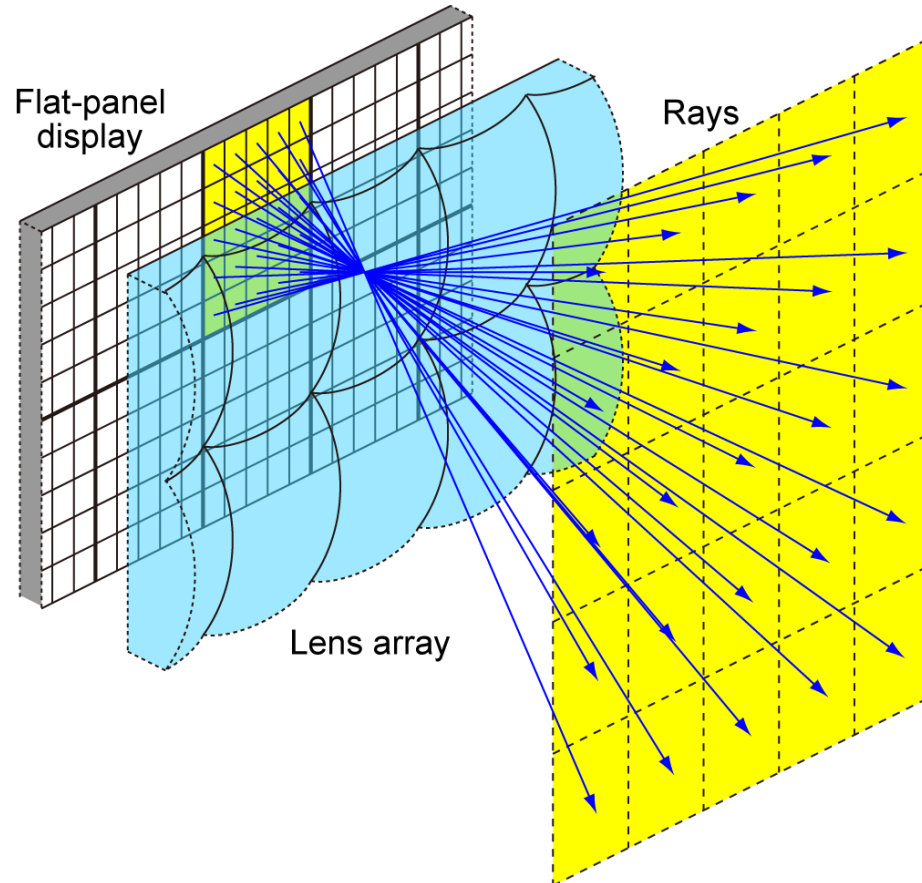
Spherical waves produce sharp points which constitute 3D images.

→ Eyes can focus on 3D images.

*The vergence-accommodation conflict does not occur.*

# Integral Imaging

*Integral imaging was invented by G. Lippmann, who was awarded the Nobel Prize in 1908. Originally, it is called “integral photography.”*



Rays from each lens can be controlled in horizontal and vertical directions.

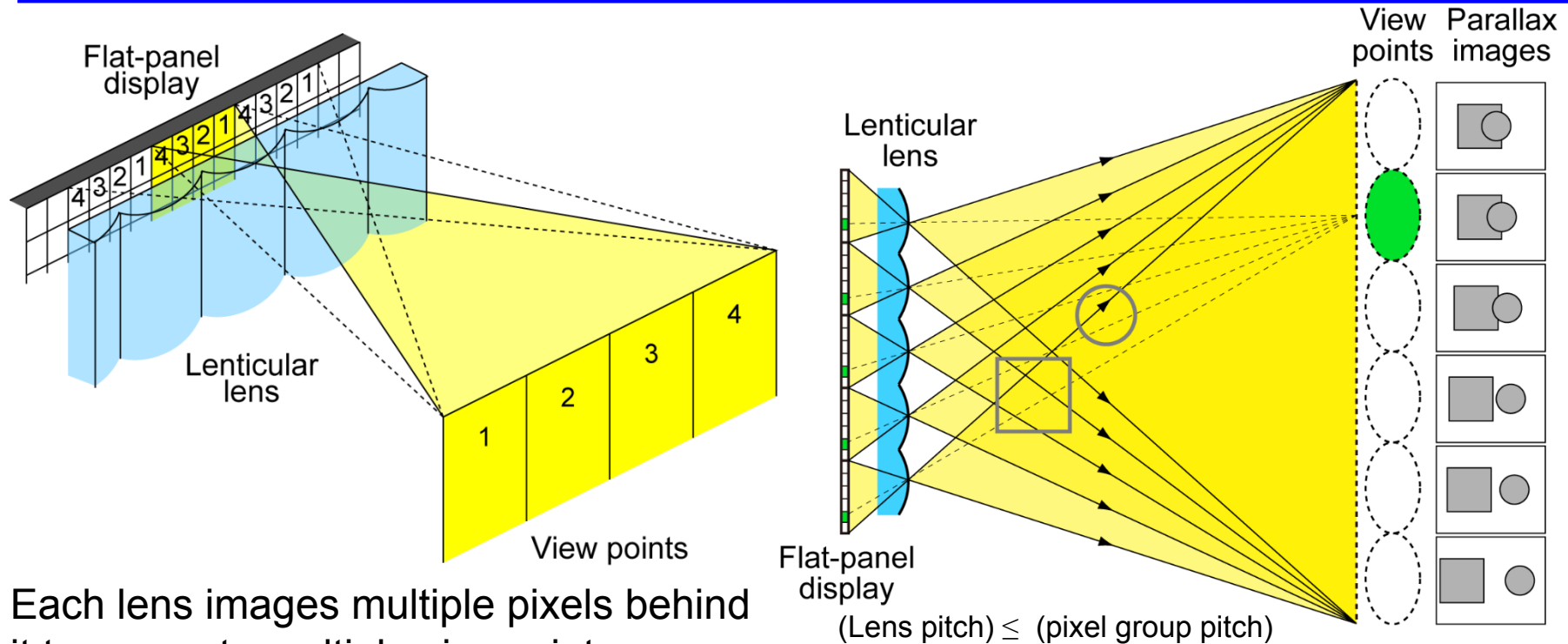
Rays emitted from 3D objects are reconstructed.

It provides 3D images with full parallax (horizontal + vertical parallaxes).

The 3D resolution is quite low.

Vergence	○
Binocular disparity	○
Accommodation	×
Motion parallax	○

# Multi-view Display



Each lens images multiple pixels behind it to generate multiple viewpoints.

Images generated by all lens are superimposed at a certain distance.

Through viewpoints, corresponding parallax images can be viewed.

3D images with horizontal parallax are provided.

(3D resolution) =

(Flat-panel resolution) / (Number of views)

Vergence

Binocular disparity

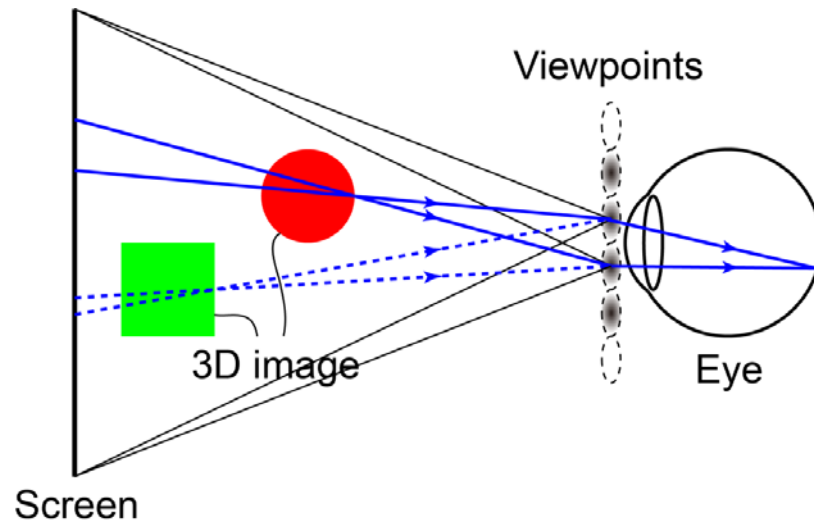
Accommodation

Motion parallax

# Super Multi-view Display Technique

The interval of viewpoints is made smaller than the pupil diameter of eyes.

→ Two or more rays passing through an identical point in the space enter the pupil simultaneously.



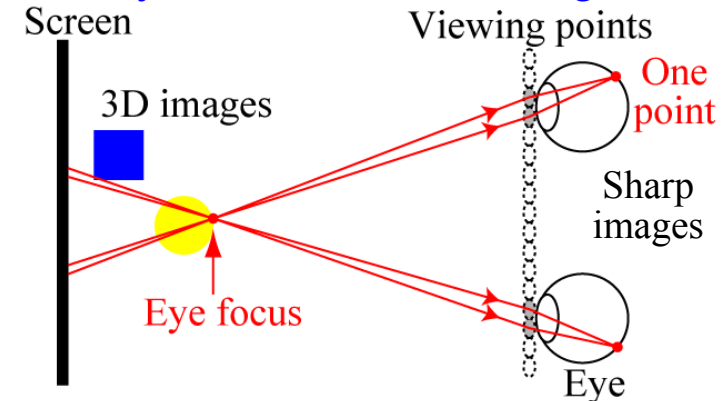
Pupil diameter: 2 ~ 8 mm (average 5 mm)

→ Interval of viewpoints: < 5 mm

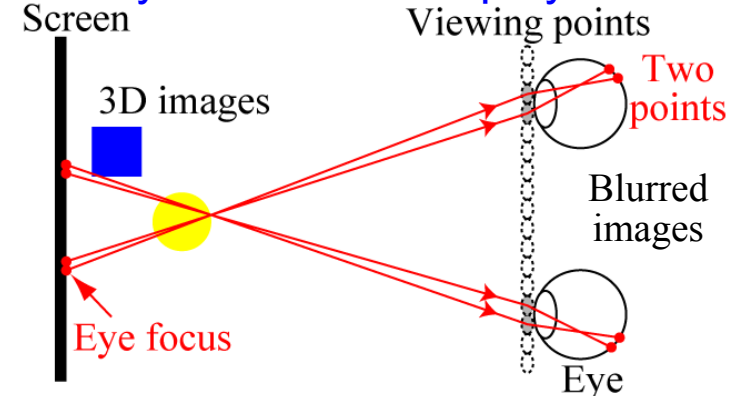
Number of viewpoints: 30 ~ 100 (horizontal)

Vergence	○
Binocular disparity	○
Accommodation	○
Motion parallax	○

When eyes focus on 3D images



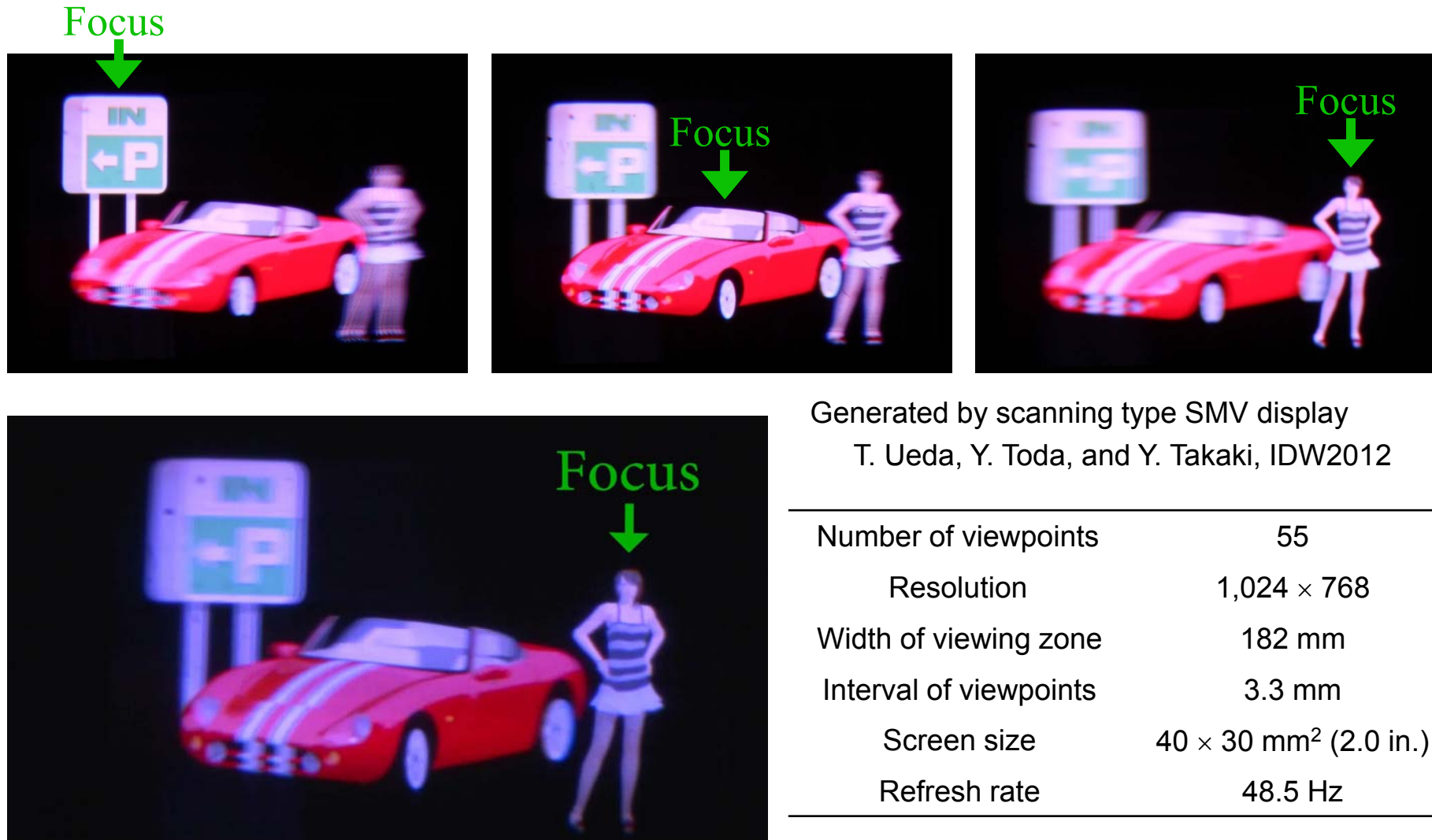
When eyes focus on display screen



Eyes can focus on 3D images.

→ The vergence-accommodation conflict does not occur.

# Video of Super Multi-view Image



Generated by scanning type SMV display  
T. Ueda, Y. Toda, and Y. Takaki, IDW2012

Number of viewpoints	55
Resolution	1,024 × 768
Width of viewing zone	182 mm
Interval of viewpoints	3.3 mm
Screen size	40 × 30 mm <sup>2</sup> (2.0 in.)
Refresh rate	48.5 Hz

# Flat-panel Type Super Multi-view Displays



Number of views: 72  
Resolution: 320 × 400  
Screen size: 22.2 in.  
4K panels is used.

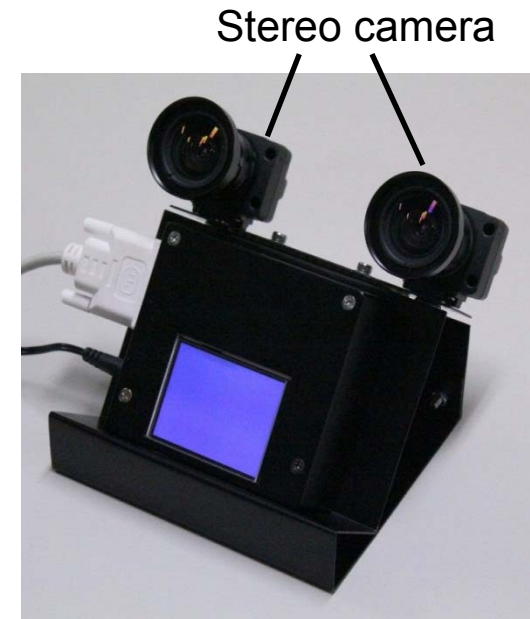
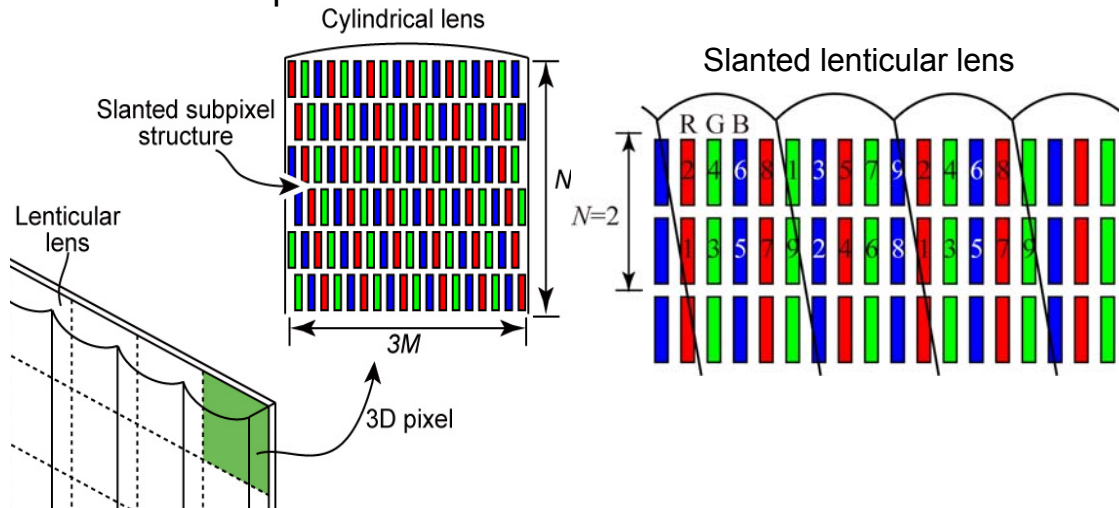


Number of views: 72  
Resolution: 640 × 400  
Screen size: 22.2 in.  
Two 4K panels are used.



Number of views: 30  
Resolution: 256 × 128  
Screen size: 7.2 in.  
Mobile use  
Developed with NTT Docomo

Flat-panel displays with slanted subpixel structure and the slanted lenticular technique are used to increase the number of views.



Eye tracking is introduced to reduce the required number of views.

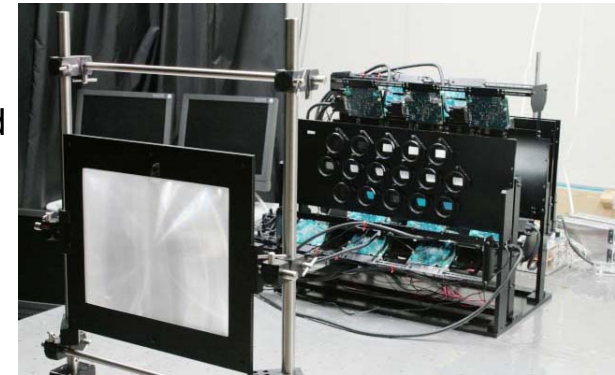
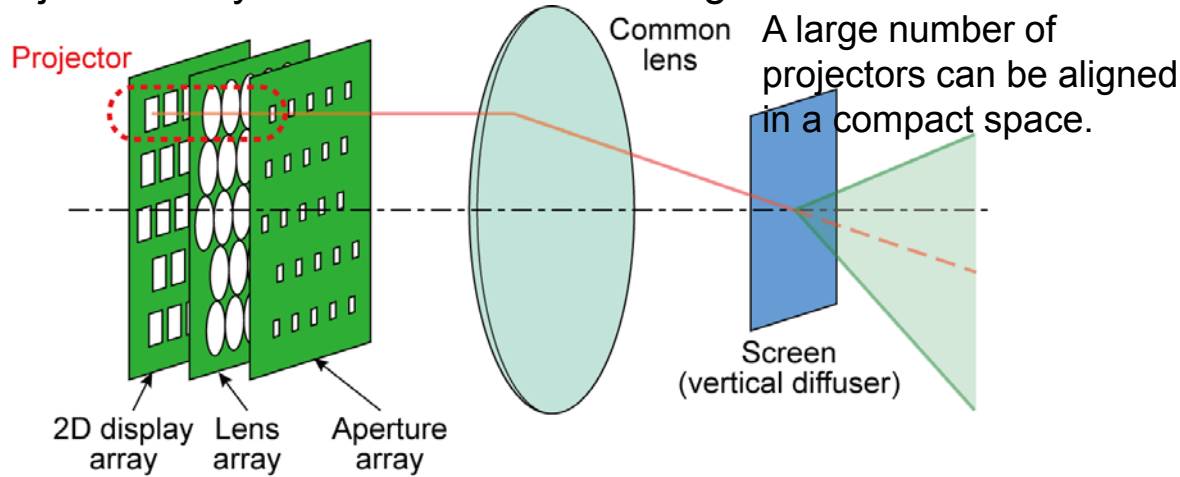
Interval of views	2.6 mm
Number of views	R 8 + L 8
Resolution	256 × 192
Screen size	2.57 in.
Observation distance	350 mm

Developed with Seiko Epson

Y. Takaki et al., Opt. Express **19**, 4129 (2011)

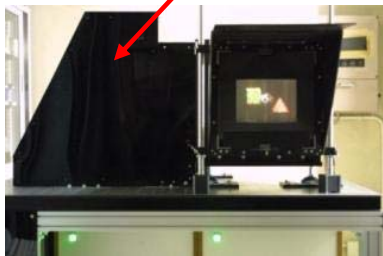
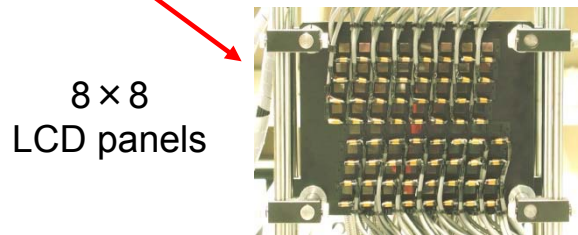
# Multi-projector Type Super Multi-view Displays

Projector array with a slanted 2D arrangement



SMV256

Number of views: 256  
Sixteen sets of 16-view displays are combined by multi-projection system.



Number of views: 64  
Resolution: ~QVGA  
Screen size: 9.25 in.



Number of views: 128  
Resolution: ~QVGA  
Screen size: 13.2 in.



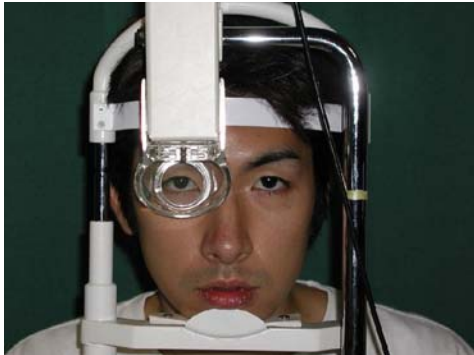
Number of views: 128  
Resolution: SVGA  
Screen size: 12.8 in.



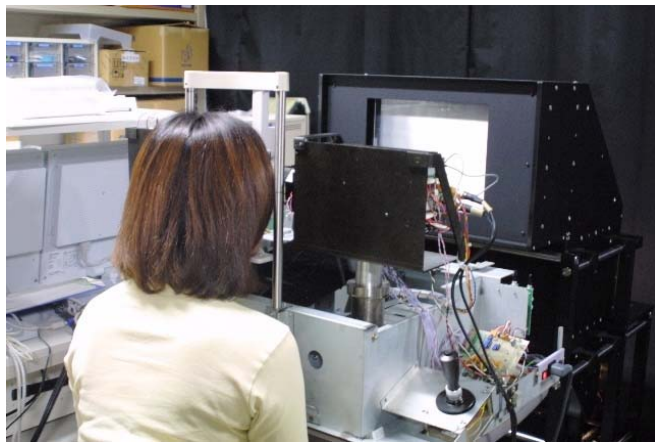
Number of views: 64  
Time multiplexing technique is used.



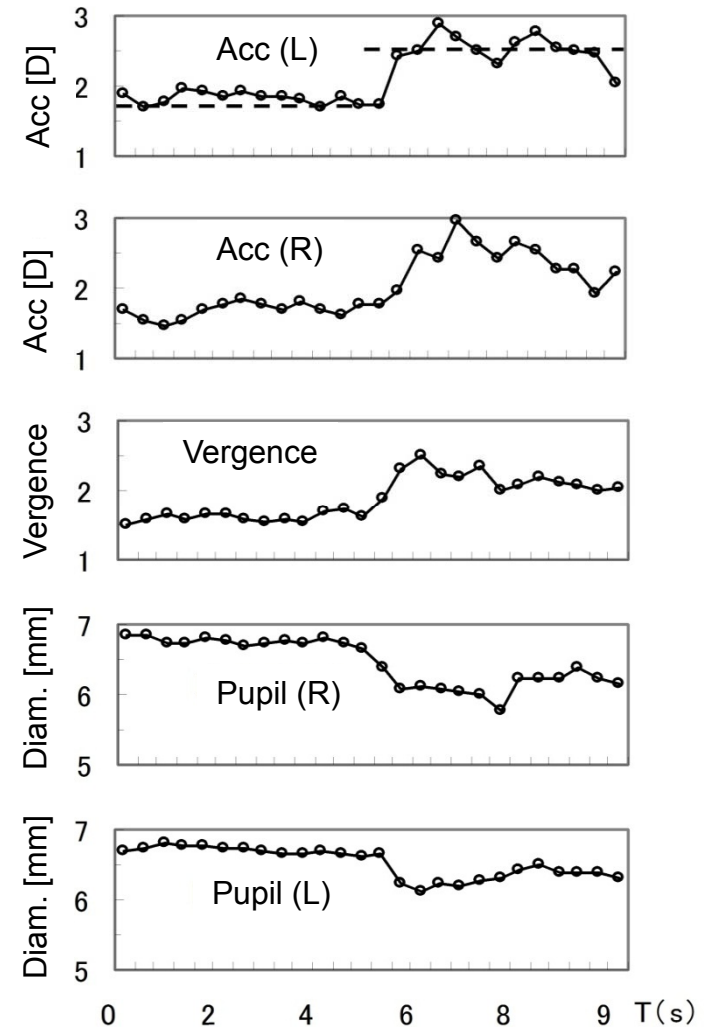
# Accommodation Measurement



Auto refractometer  
FR-5000S  
(Grand Seiko Corp.)

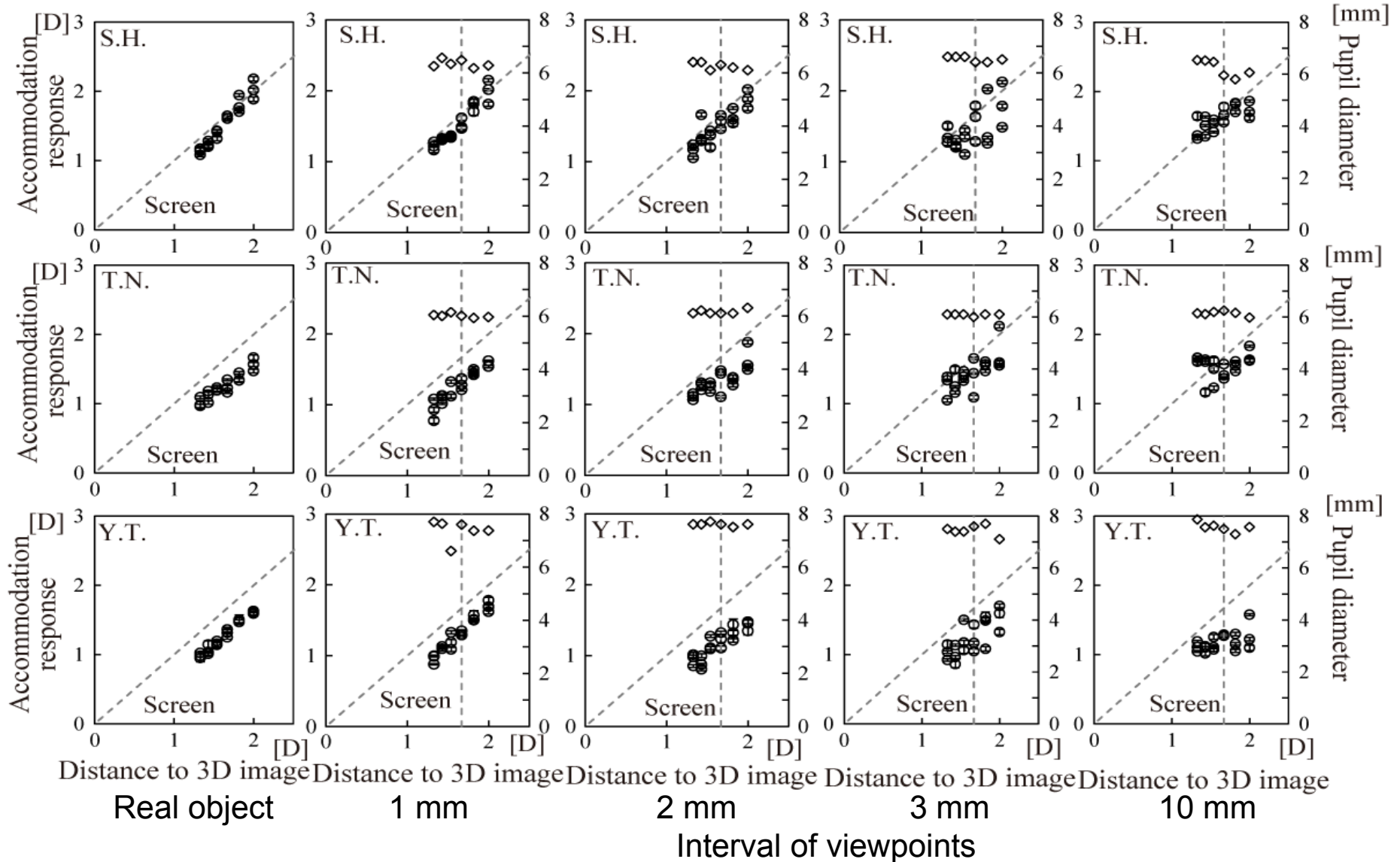


Visual function measurement equipment  
specialized for 3D displays  
Jointly developed with TOPCON Corp. under the  
SCOPE project  
R & L Accommodation + Vergence  
+ R & L Pupil diameters



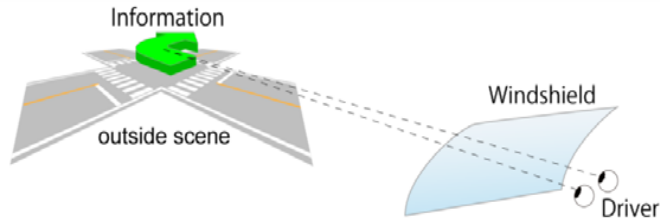
# Results of Accommodation Measurement

Diopter [D]: reciprocal of Length [m]



# Other Super Multi-view Displays

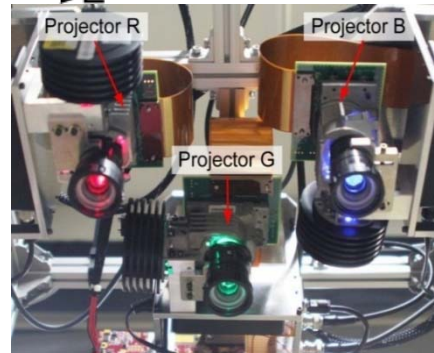
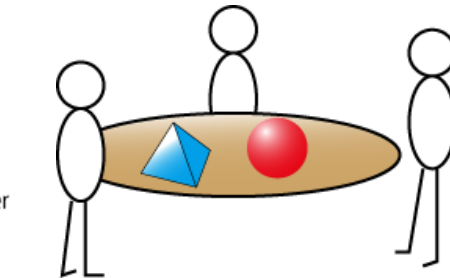
【Windshield SMV display】 【360-degree SMV display】 【Large-screen SMV display】



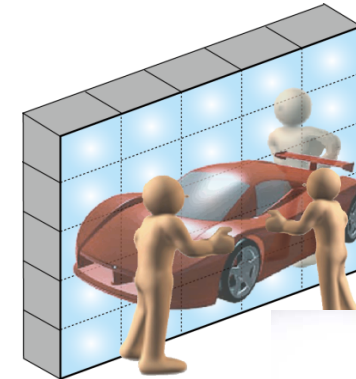
Developed with DENSO



36-view SMV-WSD



High-speed RGB projector



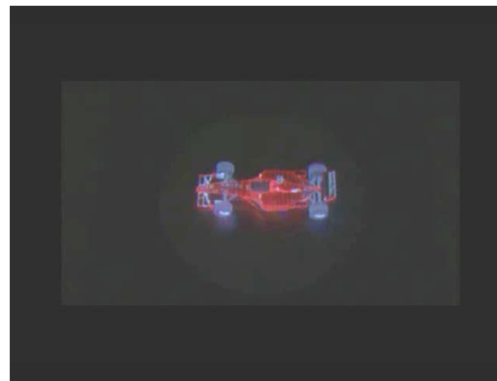
Frameless modules are tiled.



Four modules are aligned vertically.



Opt. Express 19, 704 (2011)



Opt. Express 20, 8848 (2012)

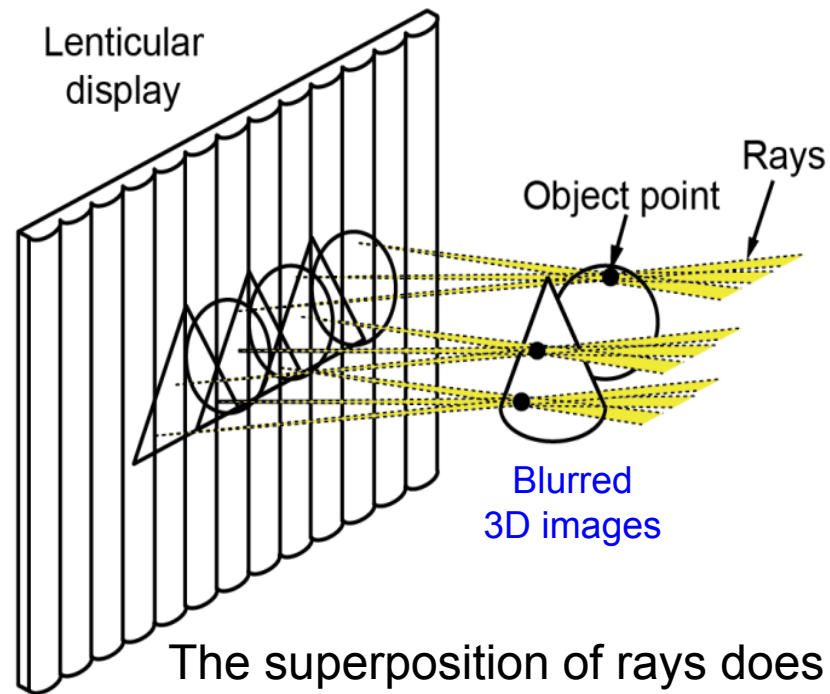


Opt. Express 19, 704 (2011)

# Ray Reconstruction v.s. Wavefront Reconstruction

## Ray reconstruction

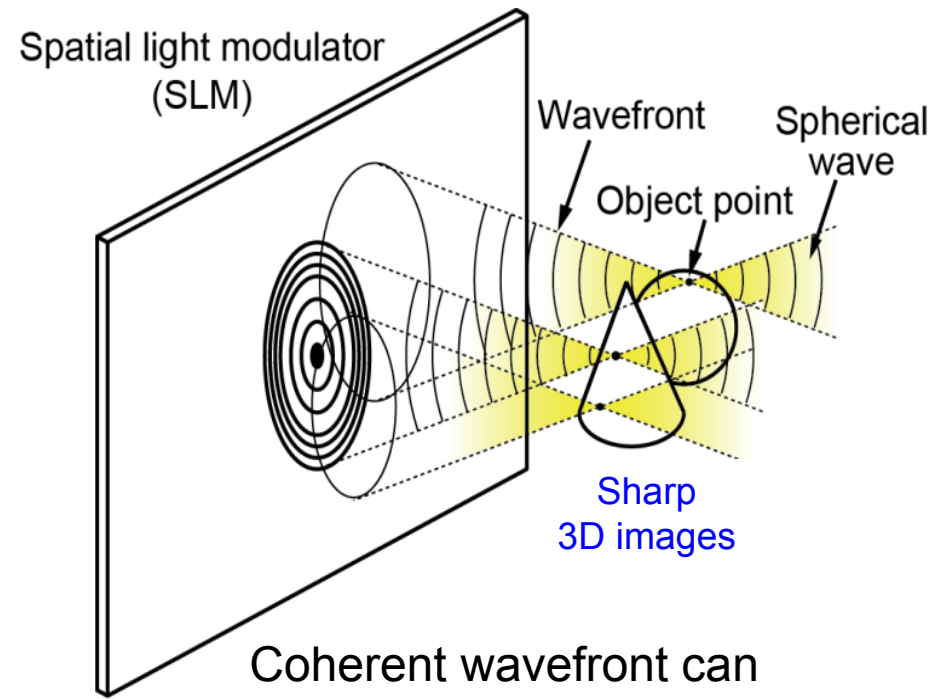
Super multi-view display



The superposition of rays does not reduce the beam width.

## Wavefront reconstruction

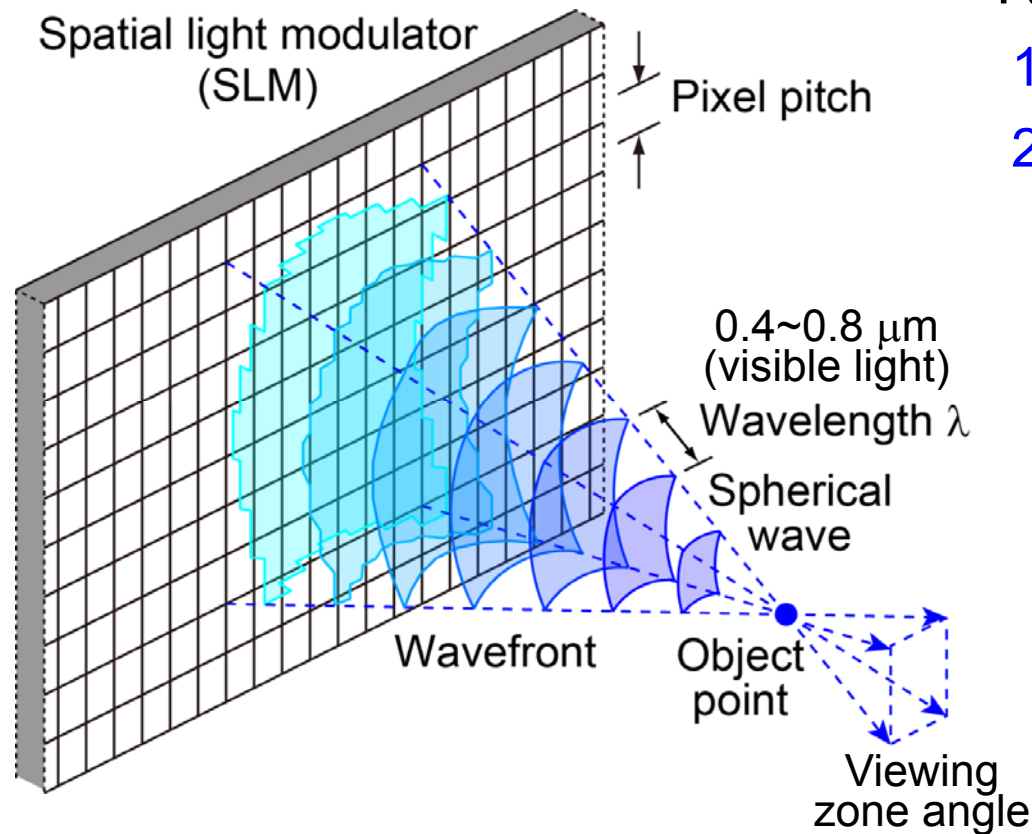
Holography



Coherent wavefront can generate sharp 3D images.

Holographic displays can produce sharper 3D images than super multi-view displays.

# Problems of Electronic Holographic Display



Requirements for SLM:

- 1) Pixel pitch needs to be  $\sim 1 \mu\text{m}$ .
- 2) To increase the screen size, the number of pixels must be proportionally increased.

Viewing zone angle:

$$\Phi = 2 \sin^{-1}(\lambda / 2p)$$

Screen size:

$$Np \times Mp$$

Pixel pitch of SLM:  $p$

Resolution of SLM:  $N \times M$

Wavelength of light:  $\lambda$

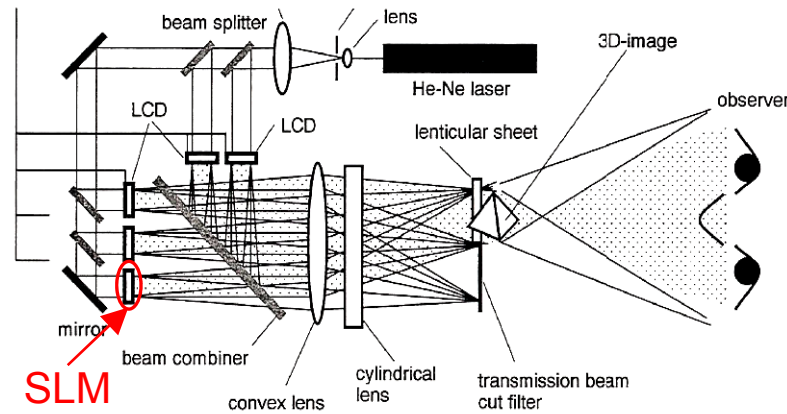
Super Hi-Vision (Ultra HD)  
Resolution:  $7,680 \times 4,320$

Screen 40 in., viewing zone angle  $30^\circ$  ( $\lambda = 0.6 \mu\text{m}$ )  
Pixel pitch:  $p = 0.97 \mu\text{m}$   
Resolution:  $N \times M = 764,000 \times 430,000$

# Previously Proposed Holographic Displays

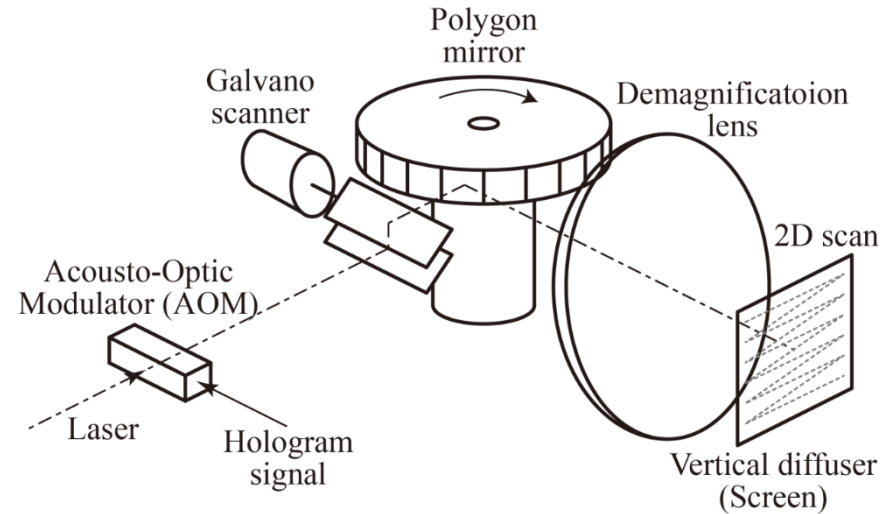
## 【Multiple SLMs】

TAO (Japan), 5 SLMs  
SPIE **2652**, 1519 (1996)

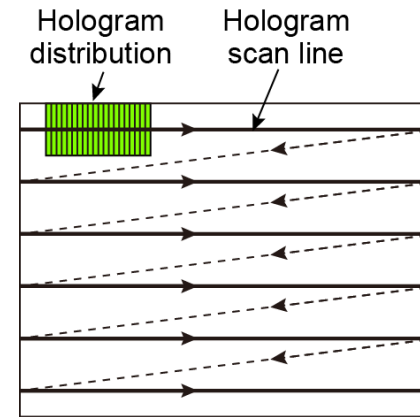
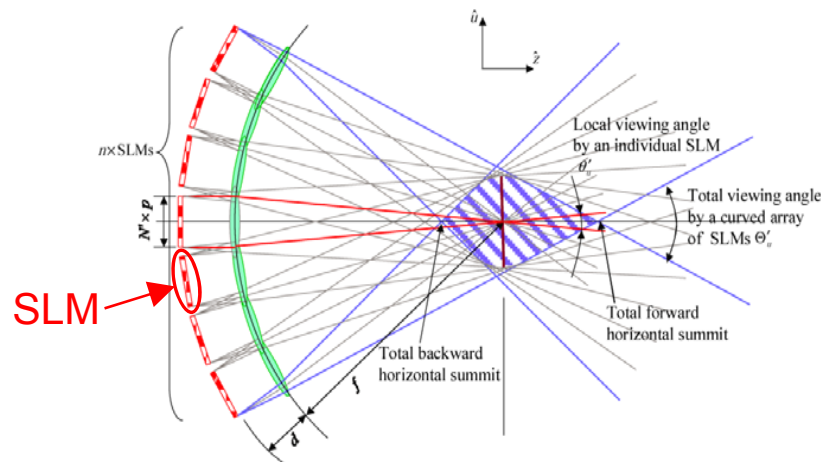


## 【AOM + 2D scanning】

MIT (U.S.A.) SPIE **1212**, 174 (1990)  
J.Opt.Soc.Am. **9**, 1969 (1992)



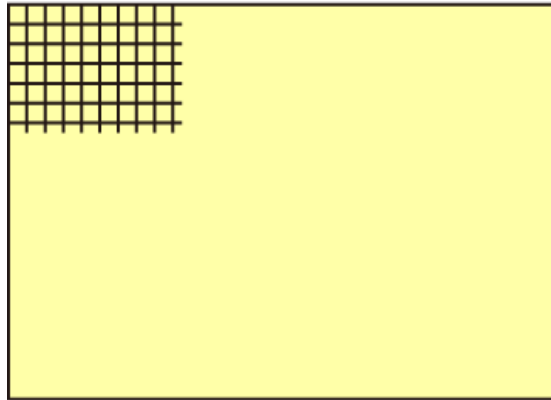
Seoul National University (Korea), 12 SLMs  
Opt. Express **16**, 12372 (2008)



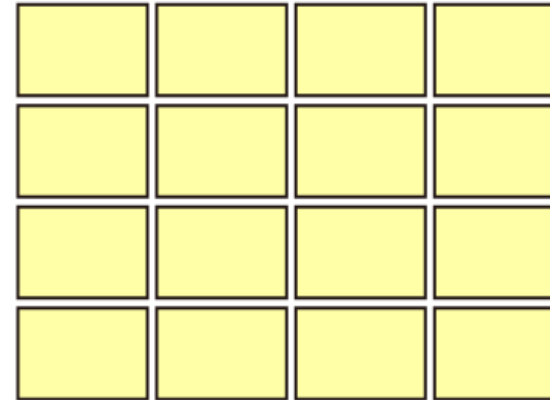
Horizontal-Parallax-Only (HPO) hologram

# Comparisons of Holographic Displays

Ultra-high resolution SLM

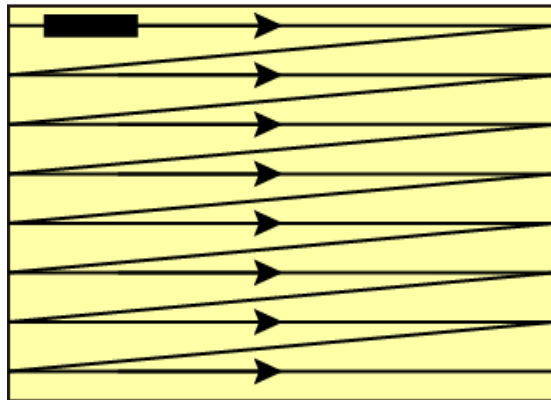


Multiple SLMs



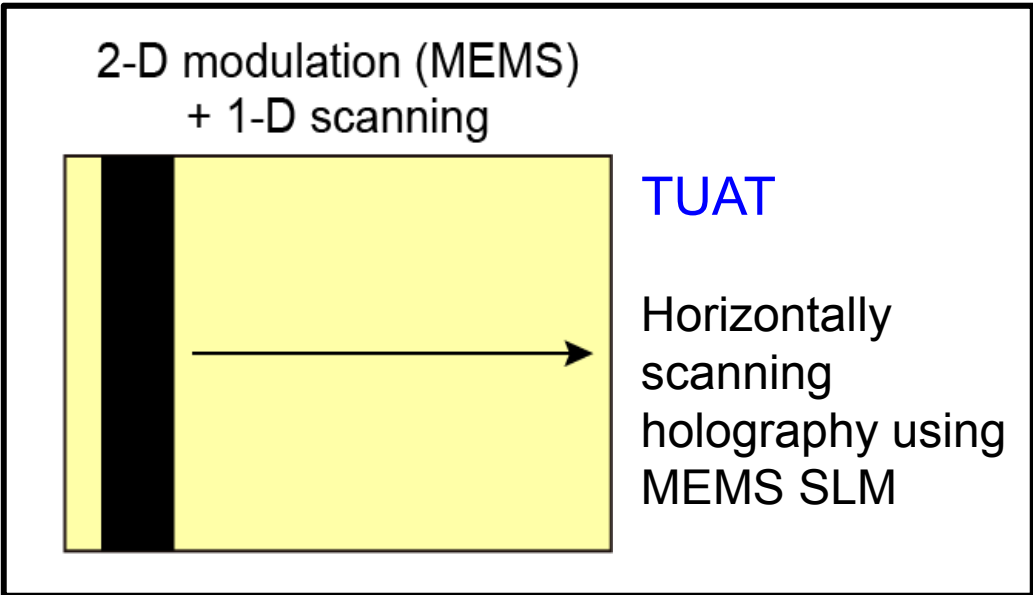
TAO, NICT  
SNU  
Bilkent Univ.

1-D modulation (AOM)  
+ 2-D scanning



MIT

2-D modulation (MEMS)  
+ 1-D scanning



TUAT

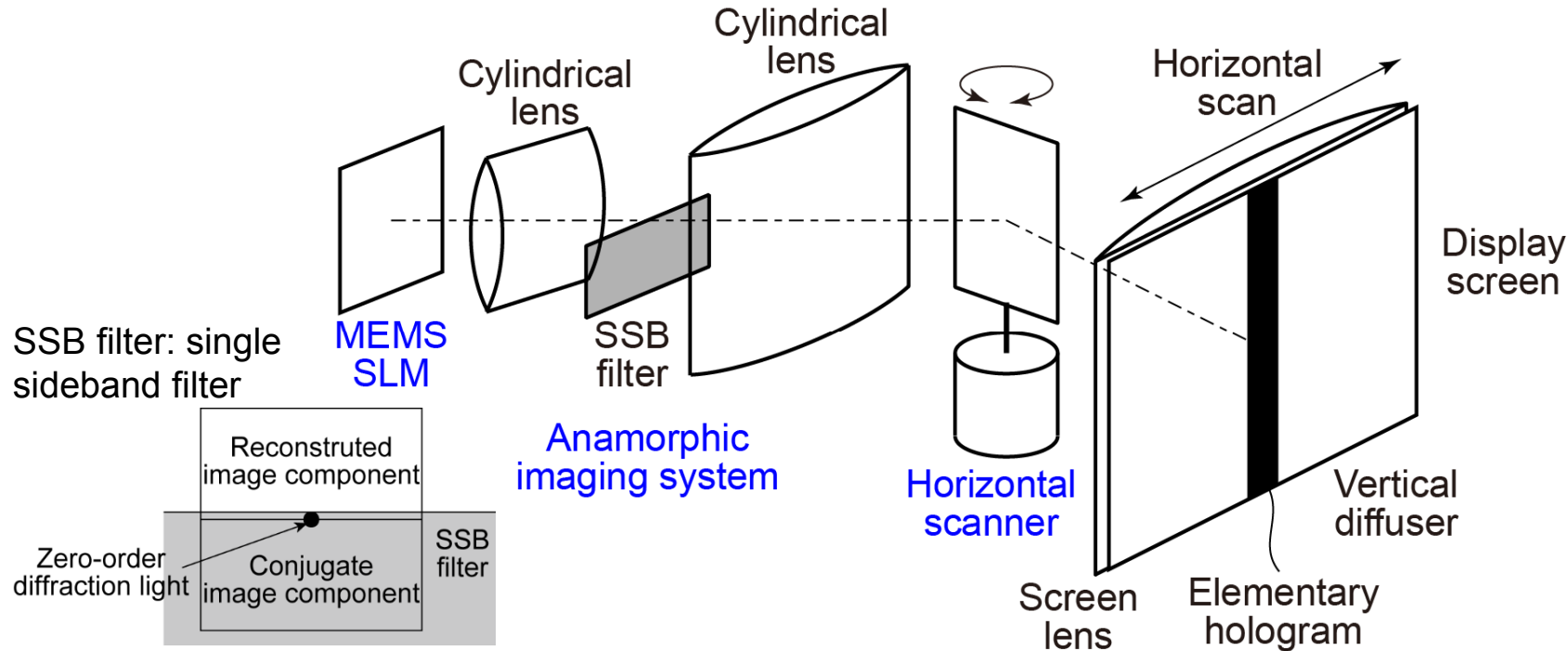
Horizontally  
scanning  
holography using  
MEMS SLM

# Horizontally Scanning Holography Using MEMS-SLM

## Screen scanning system

Y. Takaki et al., Appl. Opt. **48**, 3255 (2009)

Y. Takaki et al., Opt. Express **18**, 11327 (2010)



### Anamorphic imaging system:

Horizontal: reduce pixel pitch → Viewing zone angle increases

Vertical: increase image height

### Horizontal Scanning:

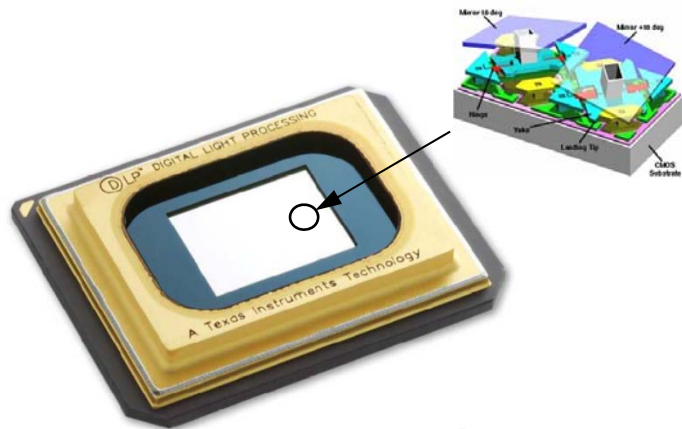
Increase image width

→ Screen size increases



# Screen Scanning System: Experimental System

## MEMS-SLM



Digital Micromirror Device  
(DMD)  
Discovery™3000

Frame rate: 13.333 kHz  
Resolution: 1,024 × 768  
Pixel pitch: 13.68 µm  
Screen size: 0.7 in.  
(14.0 × 10.5 mm<sup>2</sup>)

## Anamorphic imaging system

$$M_x = 0.183$$

$$M_y = 5.00$$

Elementary hologram  
Size: 2.56 × 52.5 mm<sup>2</sup>  
Horizontal pixel pitch:  
2.5 µm  
Horizontal viewing angle:  
15 °

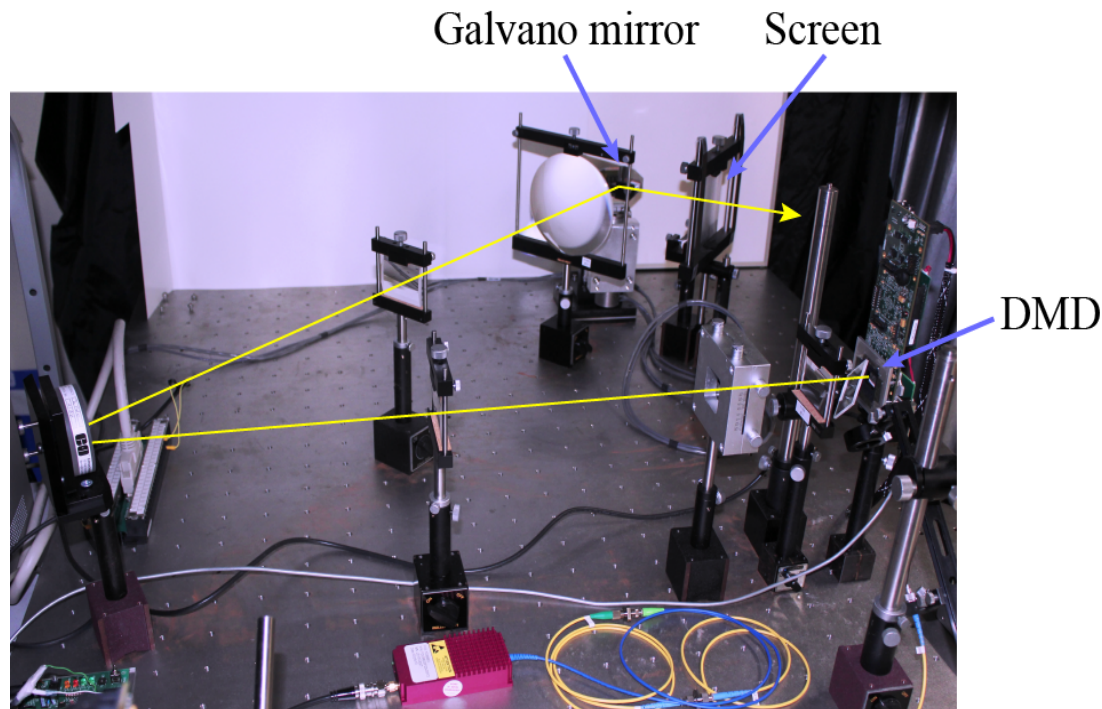
## Horizontal scanner



Galvano mirror  
MicroMax™ Series 671

Scanning frequency: 60 Hz  
Scan angle: ±18.1°  
Screen size: 3.5 in.  
(73.1 × 52.5 mm<sup>2</sup>)  
Number of elementary  
holograms: 222

# Screen Scanning System: Reconstructed Image



Symbols

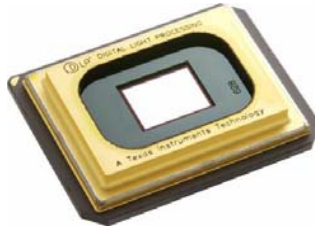
Viewing zone angle: 15°  
 Screen size: 3.5 inches  
 Frame rate: 60 Hz

# Screen Scanning System: Color System

## MEMS SLM

DMD Discovery 4100  
(Texas Instruments Inc.)

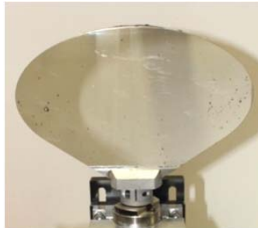
Resolution:  $1,024 \times 768$   
Pixel pitch:  $13.68 \mu\text{m}$   
Frame rate: 22.727 kHz



## Horizontal scanner

Cambridge Technology  
MicroMax™ Series671

Scan angle:  $\pm 6.8^\circ$   
Scan frequency: 30 Hz  
Mirror size:  $95 \times 170 \text{ mm}^2$



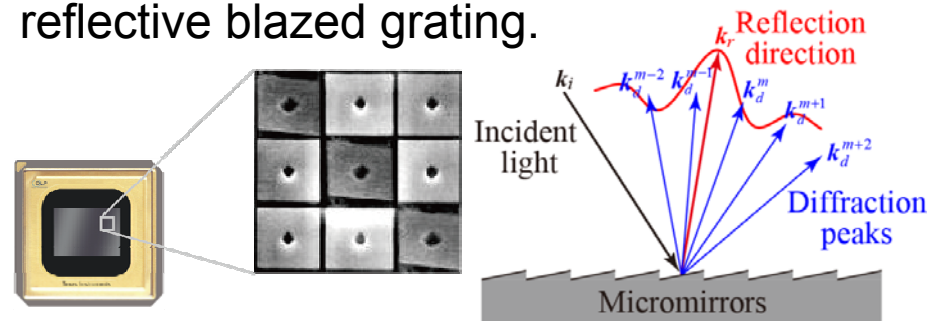
## Lasers

Toptica Photonics  
Fiber coupled laser diodes

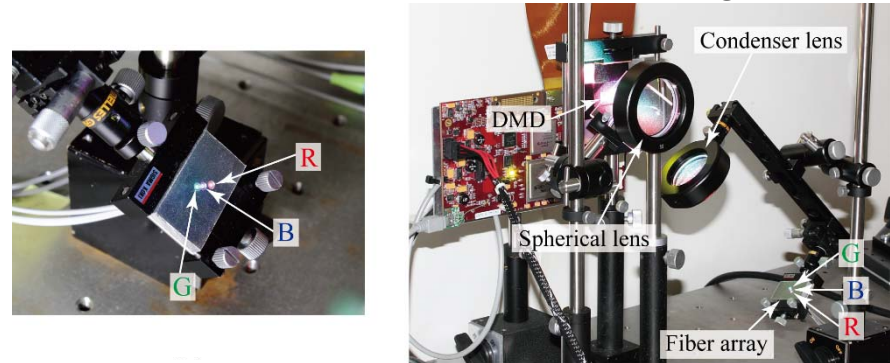


**R**: 640 nm, **G**: 515 nm, **B**: 445 nm

DMD screen has a structure similar to a reflective blazed grating.



R, G, and B laser lights should illuminate DMD with different appropriate angles.



Pixel pitch:  $2.5 \mu\text{m}$  (horizontal)

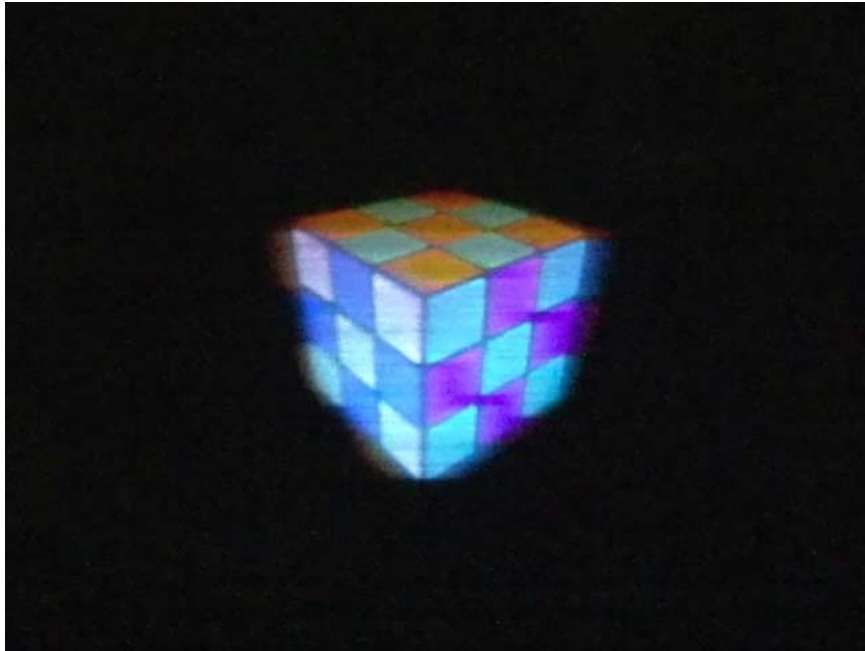
Viewing zone angles:

**Red**:  $14.7^\circ$ , **Green**:  $11.8^\circ$ , **Blue**:  $10.2^\circ$

Screen size: 6.2 inches

Frame rate (hologram): 30 Hz

# Screen Scanning System: Color Images



cube



snowman

Error diffusion technique was used to binarize elementary hologram patterns.

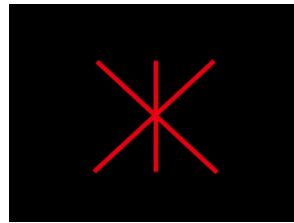
Viewing zone angles:

Red: 14.7°, Green: 11.8°, Blue: 10.2°

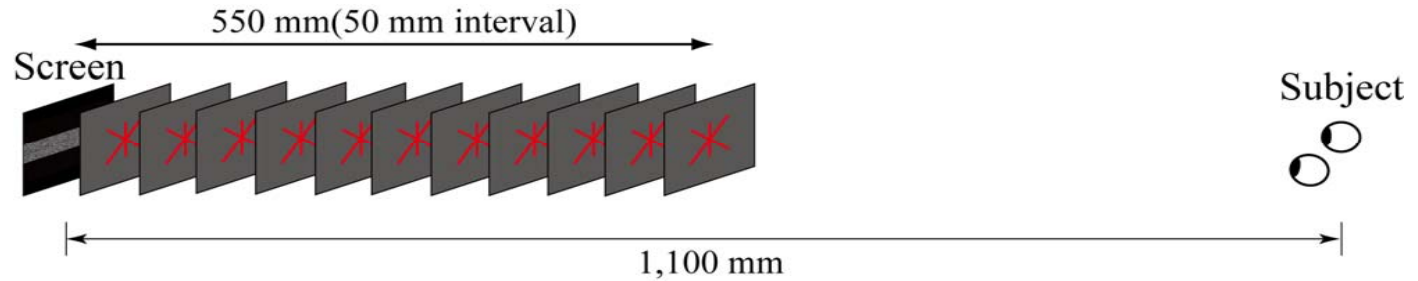
Screen size: 6.2 inches

Frame rate: 30 Hz

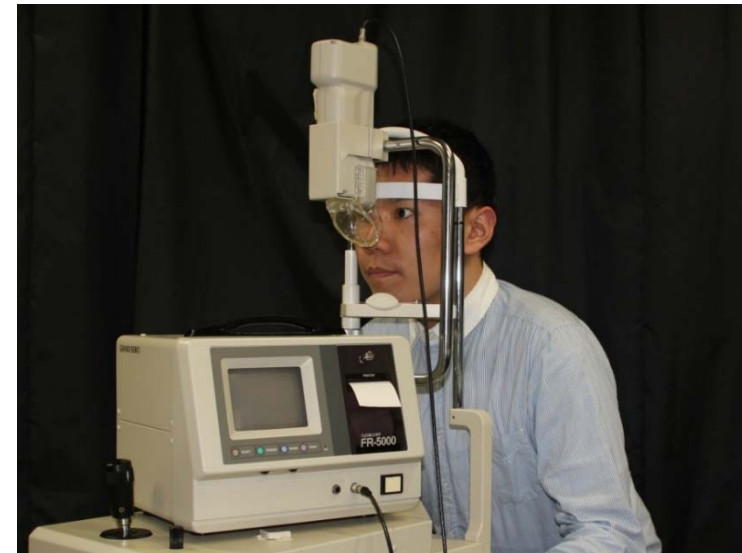
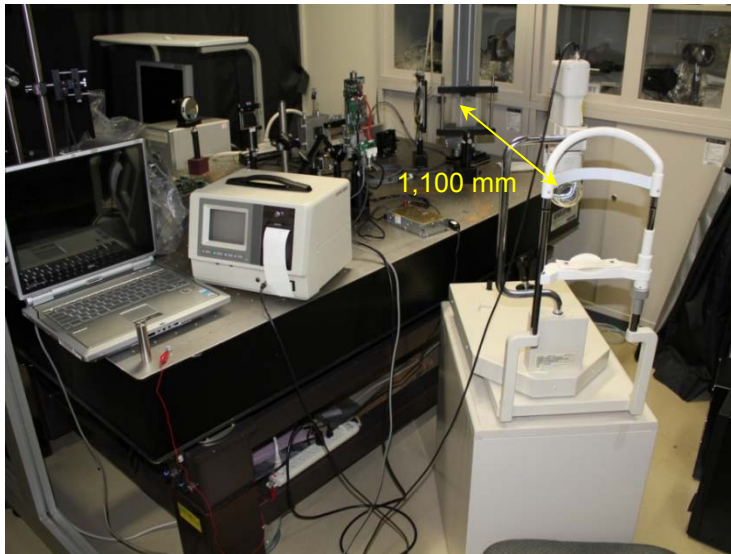
# Accommodation Measurements



Test image  
( $1.1^\circ \times 1.1^\circ$ )



The measurements were performed for 10 s, and the responses for 2 s without blink were averaged to obtain an experimental result.

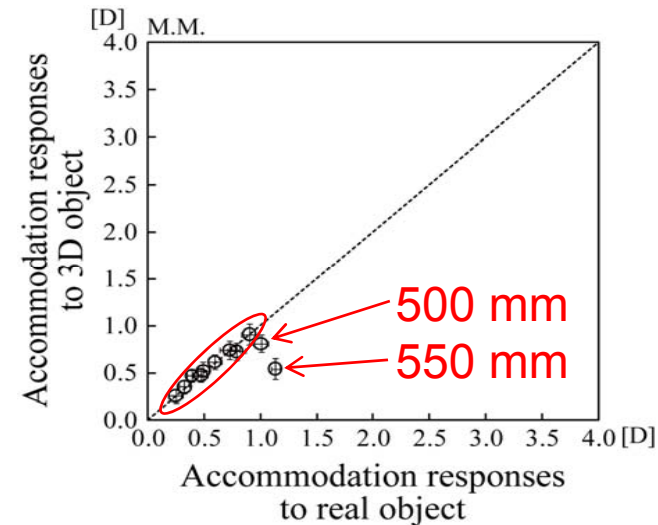
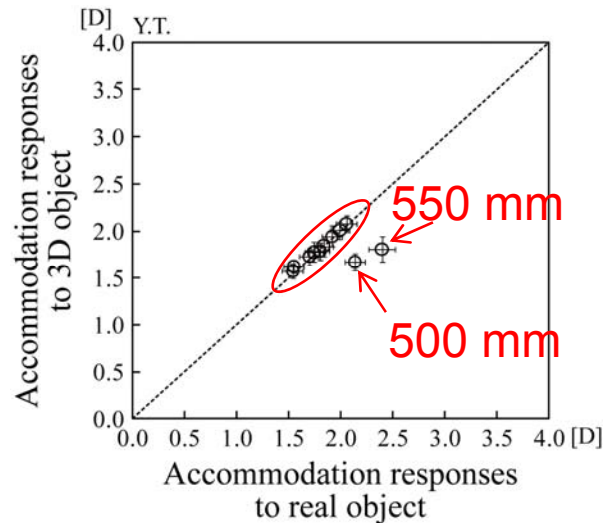
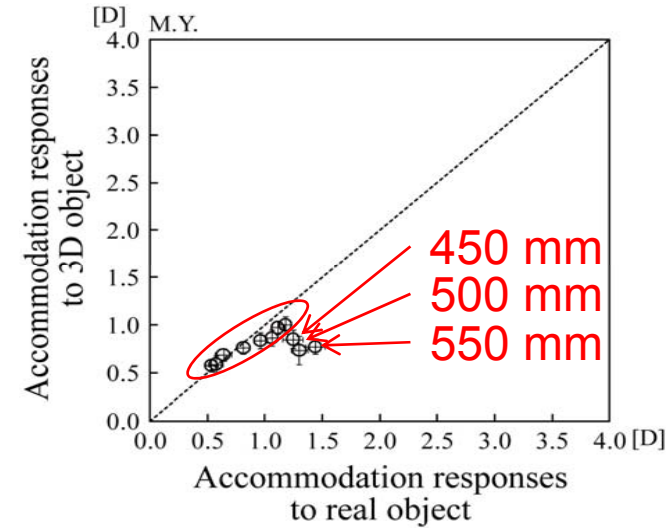
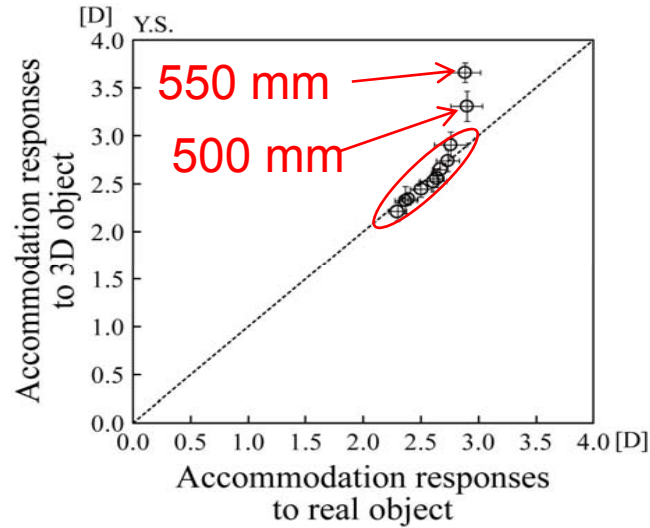


Auto refractometer: FR-5000S  
(Grand Seiko Co., Ltd.)

Y. Takaki and M. Yokouchi, Opt. Express **20**, 3918-3931 (2012)

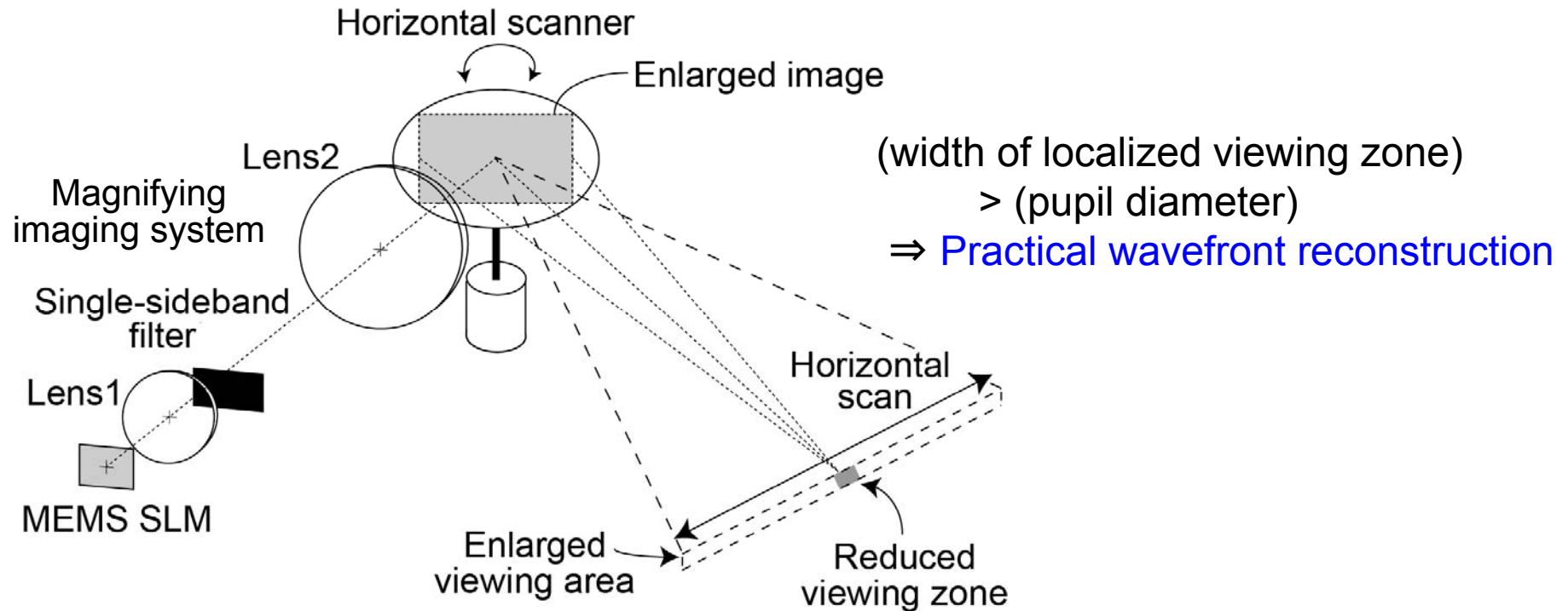
# Results of Accommodation Measurements

Diopter [D] =  
1/Length [m]



# Viewing-zone Scanning System

Y. Takaki et al., Opt. Express **22**, 24713 (2014)



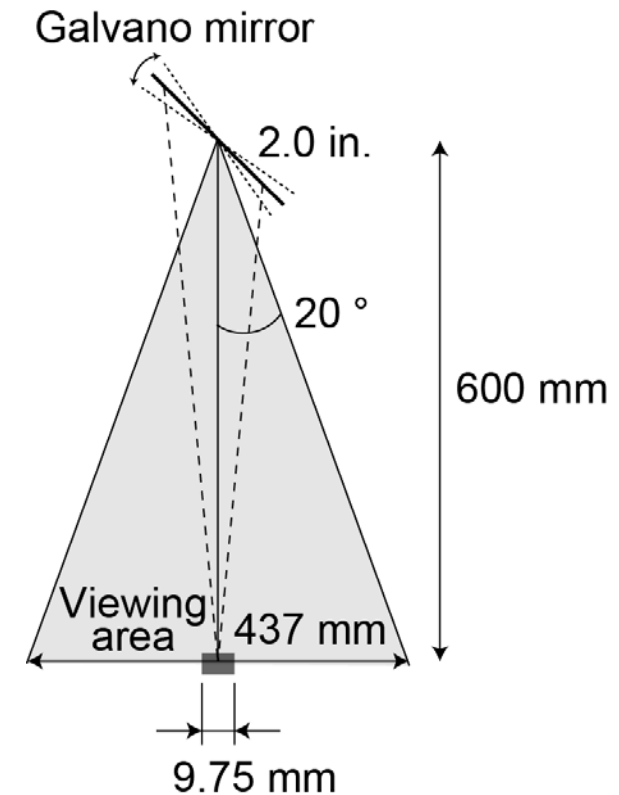
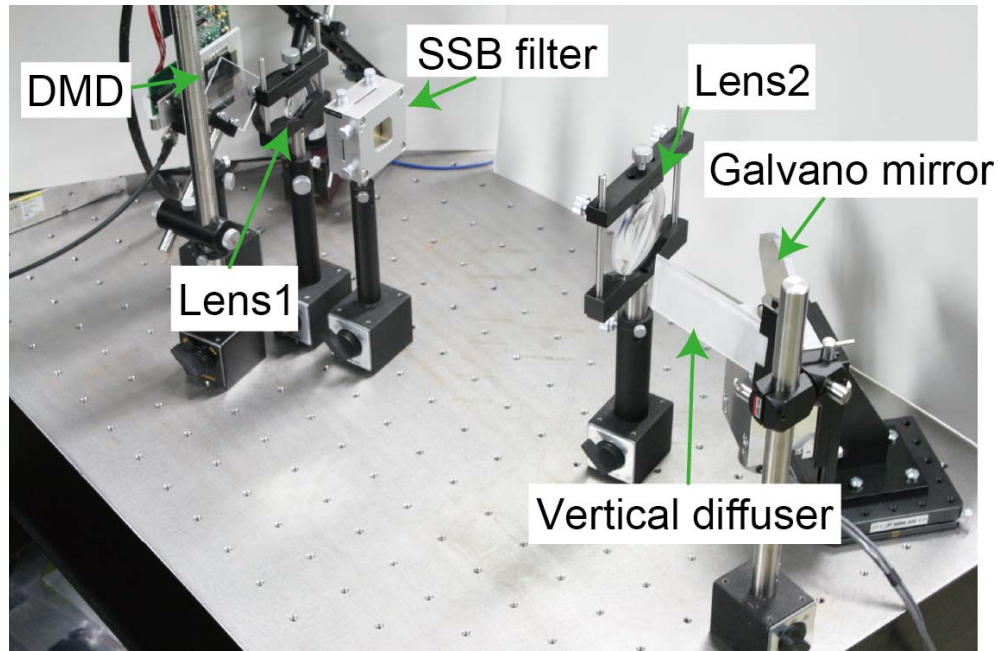
Screen size is enlarged by magnifying imaging system.

⇒ Pixel pitch increases ⇒ Viewing zone reduces

Reduced viewing zone is scanned by horizontal scanner.

⇒ Viewing zone is enlarged

## Viewing-zone Scanning System: Experimental System



Magnification of imaging system: 2.86

Screen size:  $40.0 \times 30.0 \text{ mm}^2$  (2.0 in.)

Reduced viewing zone width: 9.75 mm

Viewing zone width: 437 mm (at 600 mm)

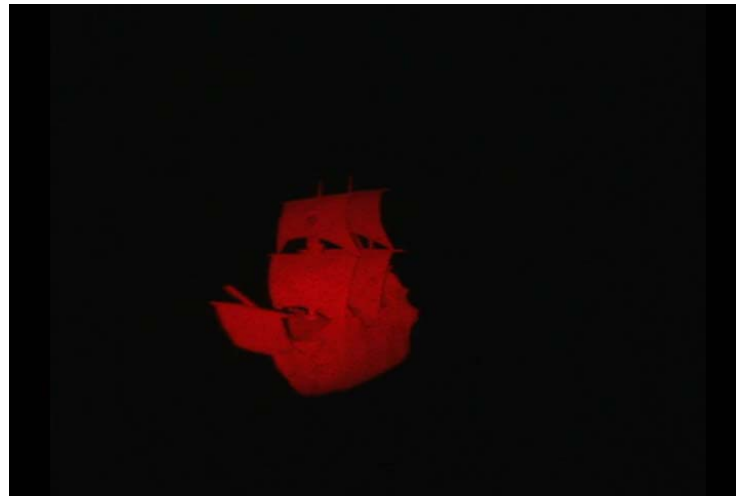
Viewing zone angle:  $40^\circ$

Frame rate: 60 Hz

Number of hologram patterns: 222



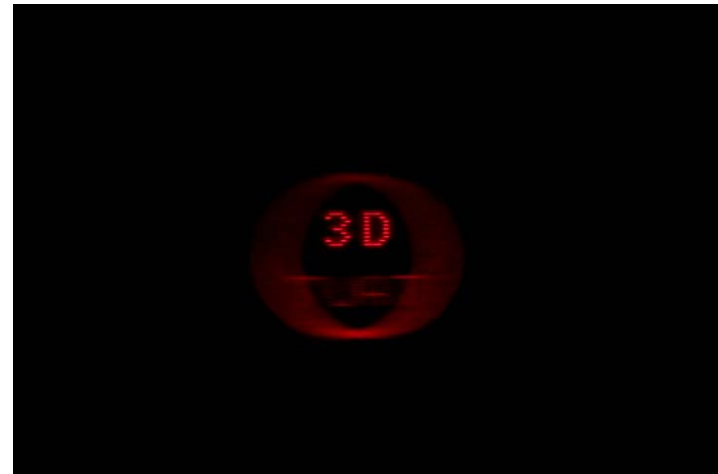
## Viewing-zone Scanning System: Reconstructed Images



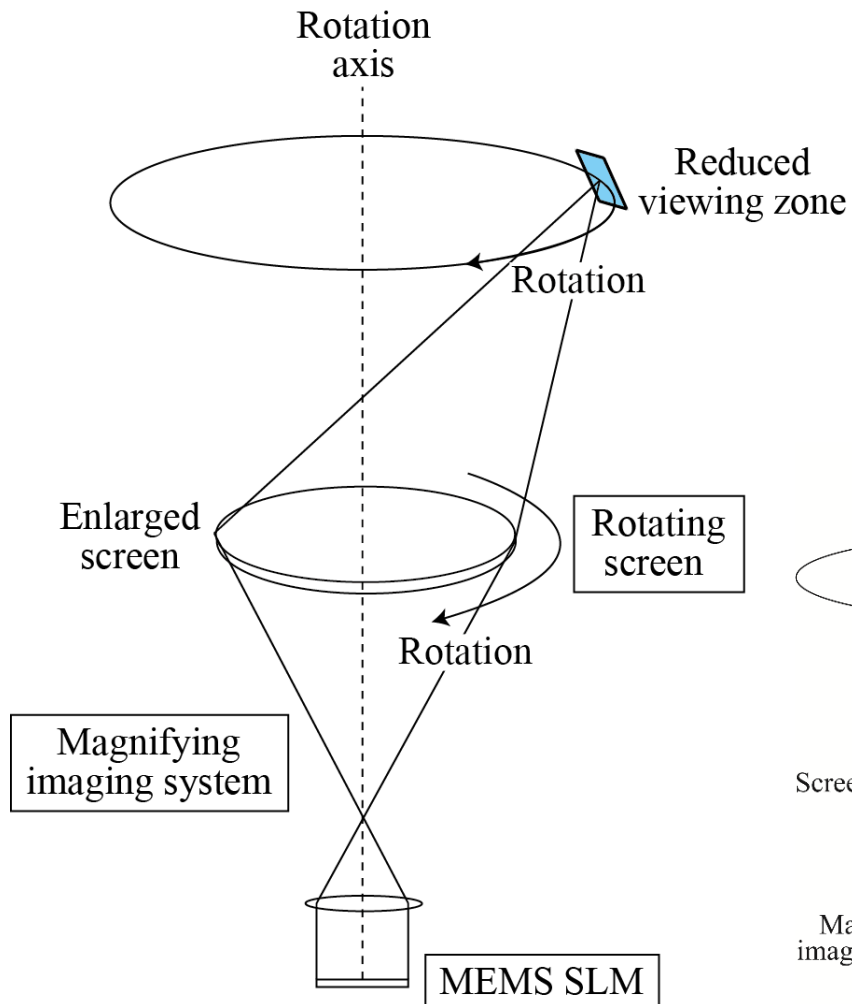
Screen size: 2.0 in.  
Viewing zone width: 437 mm (at 600 mm)  
Refresh rate: 60 Hz

Focus of camera  
was changed.

3D: +100 mm  
TUAT: +30 mm  
Circle: -100 mm



# 360-degree Scanning System



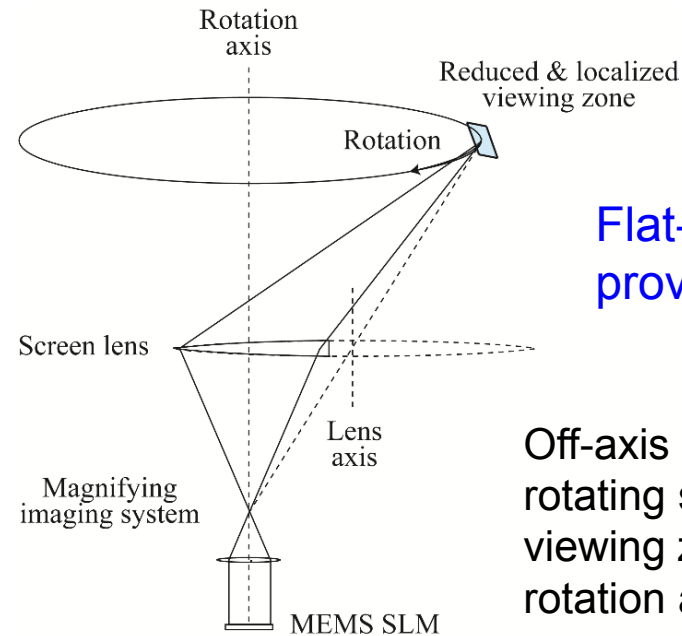
Screen size is enlarged by magnifying imaging system.

Pixel pitch increases.

→ Viewing zone reduces.

Reduced viewing zone is scanned circularly by rotating lens screen.

→ Viewing zone is enlarged to 360 degrees.

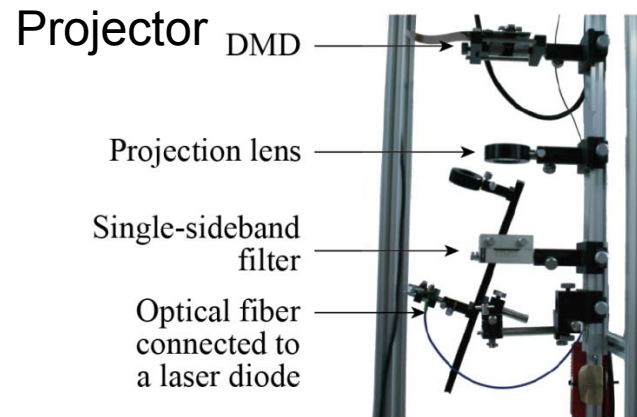


Flat-table screen is provided.

Off-axis lens is used as rotating screen to generate viewing zone outside rotation axis.

T. Inoue and Y. Takaki, Opt. Express **23**, 6533 (2015)

# 360-degree Scanning System: Experimental System



Rotating screen



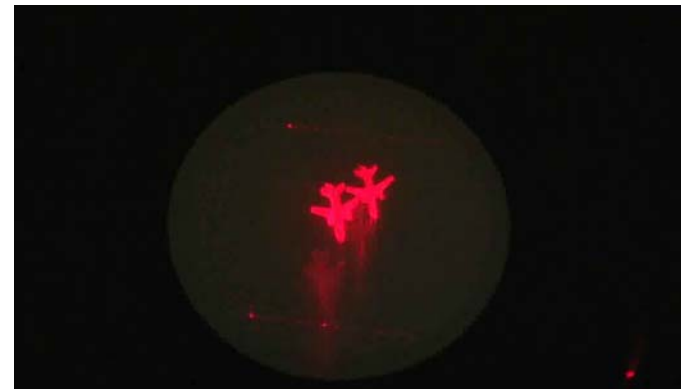
DMD: Discovery 4100  
 Frame rate: 22.727 kHz  
 Resolution: 1,024 × 768  
 Pixel pitch: 13.68 μm  
 Laser: 635 nm, 23 mW

Magnification: 5.71  
 Screen size: 80 × 60 mm<sup>2</sup>  
 (Diameter 100 mm)  
 Pixel pitch: 78.1 μm  
 Reduced viewing zone: 5.81 mm × 2.91 mm

Rotation speed: 1,700 rpm  
 Number of hologram / rotation: 800  
 Frame rate (3D): 28.4 Hz



3D: 110 mm, TUAT: 90 mm, circle: 70 mm



plane1: 90 mm, plane2: 110 mm

# Requirement for Display Devices

Screen size: 40 in. (886 mm × 498 mm)

Frame rate: 60 Hz

## Display technology:

Holography (pixel pitch: 1  $\mu\text{m}$ )

full-parallax: 441 Gpixels

HPO: 956 Mpixels

SMV (resolution: 1920 × 1080)

full-parallax: 256 × 128 views: 70 Gpixels

HPO: 256 views: 531 Mpixels

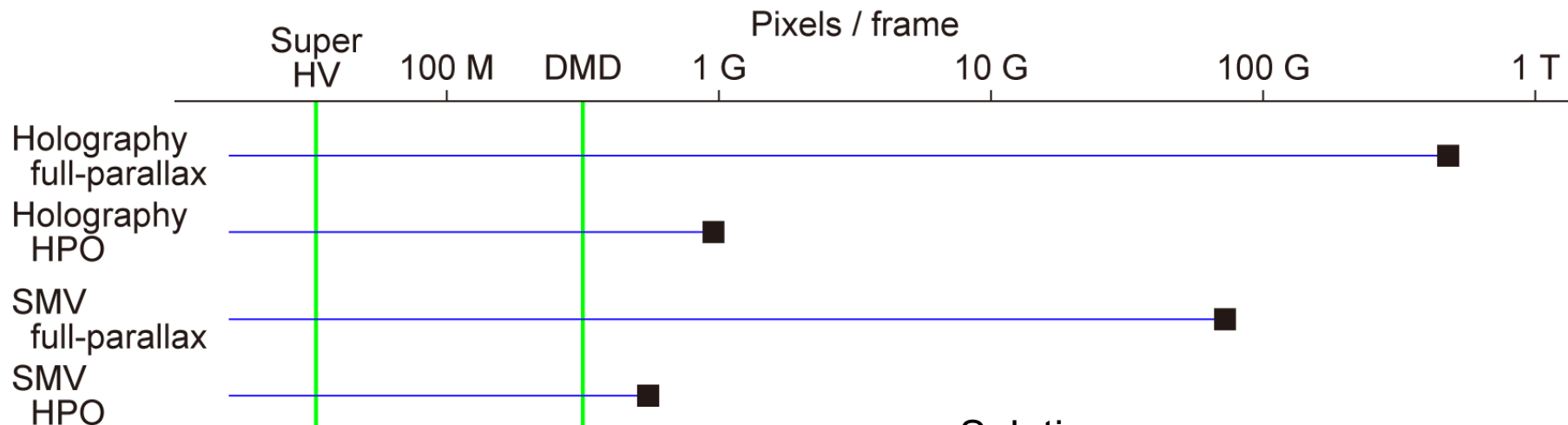
## Device technology:

Full HD: 2 Mpixels

4K: 8 Mpixels

Super HV: 33 Mpixels

DMD: 300 Mpixels (binary)



## Solutions:

Use of multiple devices

Eye tracking / Face tracking

# Summary

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*The next-generation 3D displays should be free from visual fatigue caused by the vergence-accommodation conflict, and also provide smooth motion parallax.*

*Holography and SMV displays are candidates for the next-generation 3D displays.*

*Several types of the SMV displays, the scanning holography using MEMS SLM, and the accommodation responses were shown.*

*The requirement for display devices to realize these displays was discussed.*

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